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**RESEARCH ARTICLE**

# A note on Keakeya sets of horizontal and $SL(2)$ lines

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**Abstract**

We consider unions of  $SL(2)$  lines in  $\mathbb{R}^3$ . These are lines of the form

$$L = (a, b, 0) + \text{span}(c, d, 1),$$

where  $ad - bc = 1$ . We show that if  $\mathcal{L}$  is a Keakeya set of  $SL(2)$  lines, then the union  $\cup \mathcal{L}$  has Hausdorff dimension 3. This answers a question of Wang and Zahl. The  $SL(2)$  lines can be identified with *horizontal lines* in the first Heisenberg group, and we obtain the main result as a corollary of a more general statement concerning unions of horizontal lines. This statement is established via a point-line duality principle between horizontal and *conical lines* in  $\mathbb{R}^3$ , combined with recent work on *restricted families of projections to planes*, due to Gan, Guo, Guth, Harris, Maldague and Wang. Our result also has a corollary for Nikodym sets associated with horizontal lines, which answers a special case of a question of Kim.

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**1 | INTRODUCTION**

The purpose of this note is to study the Hausdorff dimension of unions of  $SL(2)$  lines in  $\mathbb{R}^3$ . Here is the definition of  $SL(2)$  lines, following [10].

**Definition 1.1** ( $\mathcal{L}_{SL(2)}$ ). The family  $\mathcal{L}_{SL(2)}$  consists of the following lines  $L \subset \mathbb{R}^3$ . Either  $L$  is a line contained in the  $xy$ -plane, and  $0 \in L$ , or then

$$L := L_{\alpha,\beta,\gamma,\delta} := (\alpha, \beta, 0) + \text{span}(\gamma, \delta, 1),$$

where  $\alpha\delta - \beta\gamma = 1$ .

We also use the following notation. If  $\mathcal{L}$  is any family of lines in  $\mathbb{R}^3$ , we write  $\text{dir}(\mathcal{L}) := \{e \in S^2 : \ell \parallel \text{span}(e) \text{ for some } \ell \in \mathcal{L}\}$ . Here is the main result of the note.

**Theorem 1.2.** *Let  $\mathcal{L} \subset \mathcal{L}_{SL(2)}$  be a set with  $\mathcal{H}^2(\text{dir}(\mathcal{L})) > 0$ . Then*

$$\dim_{\mathbb{H}}(\cup \mathcal{L}) = 3.$$

Here ‘ $\dim_{\mathbb{H}}(\cup \mathcal{L})$ ’ is the Euclidean Hausdorff dimension of the union  $\cup \mathcal{L} := \bigcup_{\ell \in \mathcal{L}} \ell$ .

*Remark 1.3.* Theorem 1.2 answers a question posed by Wang and Zahl in [10, Section 1.2]. This question was motivated by earlier work of Katz and Zahl [5]. Theorem 1.2 continues to hold if the full lines in  $\mathcal{L}$  are replaced by line segments of positive length. We will discuss this briefly below (3.2).

Katz, Wu and Zahl [4] also proved Theorem 1.2 independently, using a different method.

The  $SL(2)$  lines are essentially (up to a change in coordinates) the same as *horizontal lines in the first Heisenberg group*  $\mathbb{H} = (\mathbb{R}^3, *)$ , viewed as subsets of  $\mathbb{R}^3$  (see Proposition 2.1). We will infer Theorem 1.2 from a more general statement concerning unions of these horizontal lines, Theorem 1.5 below. We first need to define the concepts properly.

The family of all horizontal lines is denoted by  $\mathcal{L}(\mathbb{H})$ . The ‘Heisenberg’ definition of these lines is the following. Let  $\Pi_0 := \{(x, y, 0) : x, y \in \mathbb{R}\}$  be the  $xy$ -plane, and for  $p \in \mathbb{R}^3$ , let  $\Pi_p := p * H_0$  be the *left translate* of  $\Pi_0$  by the Heisenberg group product

$$(x, y, t) * (x', y', t') = \left(x + x', y + y', t + t' + \frac{1}{2}(xy' - x'y)\right).$$

Then,  $\mathcal{L}(\mathbb{H})$  consists of all the lines in  $\Pi_p$  (for every  $p \in \mathbb{R}^3$ ) which contain the point  $p$ .

The family  $\mathcal{L}(\mathbb{H})$  is a three-dimensional submanifold of the full (four-dimensional) family of lines in  $\mathbb{R}^3$ . In fact, the definition above of horizontal lines will not be used in the note: rather, we

focus attention on the following parameterised subset of  $\mathcal{L}(\mathbb{H})$ :

$$\mathcal{L}'(\mathbb{H}) = \{\ell_{(a,b,c)} : (a, b, c) \in \mathbb{R}^3\},$$

where

$$\ell_{(a,b,c)} = \left\{ (as + b, s, \frac{b}{2}s + c) : s \in \mathbb{R} \right\}.$$

The subset  $\mathcal{L}'(\mathbb{H})$  consists of all elements of  $\mathcal{L}(\mathbb{H})$ , except for those contained in some translate of the plane  $\mathbb{W}_0 := \{(x, 0, t) : x, t \in \mathbb{R}\}$ . By definition, every set  $\mathcal{L} \subset \mathcal{L}'(\mathbb{H})$  can be written as

$$\mathcal{L} = \ell(P) := \{\ell_{(a,b,c)} : (a, b, c) \in P\}$$

for some set  $P \subset \mathbb{R}^3$ . This identification of  $\mathcal{L}'(\mathbb{H})$  with  $\mathbb{R}^3$  allows us to transport notions like ‘Borel set’ and ‘dimension’ from  $\mathbb{R}^3$  to corresponding notions for subsets of  $\mathcal{L}'(\mathbb{H})$ .

**Definition 1.4.** Let  $\mathcal{L} = \ell(P) \subset \mathcal{L}'(\mathbb{H})$ . We say that  $\mathcal{L}$  is a Borel set if  $P \subset \mathbb{R}^3$  is a Borel set. We define  $\dim_{\mathbb{H}} \mathcal{L} := \dim_{\mathbb{H}} P$ , where ‘ $\dim_{\mathbb{H}} P$ ’ refers to the Euclidean Hausdorff dimension of  $P \subset \mathbb{R}^3$ .

Now we can state our main result about unions of horizontal lines.

**Theorem 1.5.** *Let  $\mathcal{L} \subset \mathcal{L}'(\mathbb{H})$ . Then,*

$$\dim_{\mathbb{H}}(\cup \mathcal{L}) = \min\{\dim_{\mathbb{H}} \mathcal{L} + 1, 3\}.$$

The following corollary implies Theorem 1.2, as we will verify in Section 2.

**Corollary 1.6.** *Let  $\mathcal{L} \subset \mathcal{L}(\mathbb{H})$  with  $\mathcal{H}^2(\text{dir}(\mathcal{L})) > 0$ . Then,*

$$\dim_{\mathbb{H}}(\cup \mathcal{L}) = 3.$$

*Remark 1.7.* Theorem 1.5 and Corollary 1.6 continue to hold if full lines are replaced by line segments of positive length, see the discussion below (3.2). Thus, if  $\mathcal{L} \subset \mathcal{L}'(\mathbb{H})$ , and every line  $\ell \in \mathcal{L}$  contains a segment  $I(\ell) \subset \ell$  of positive length, then

$$\dim_{\mathbb{H}} \left( \bigcup_{\ell \in \mathcal{L}} I(\ell) \right) = \min\{\dim_{\mathbb{H}} \mathcal{L} + 1, 3\}. \tag{1.8}$$

### 1.1 | Nikodym sets associated with horizontal lines

Theorem 1.5 easily yields information about the dimension of *Nikodym sets* associated with horizontal lines. A set  $N \subset \mathbb{R}^3$  is called an  $\mathcal{L}(\mathbb{H})$ -*Nikodym set* if for every  $p \in \mathbb{R}^3$  (or more generally every  $p \in \mathbb{R}^3$  in a measurable set of positive measure  $\Omega \subset \mathbb{R}^3$ ), there exists a line  $\ell_p \in \mathcal{L}(\mathbb{H})$  containing  $p$  such that  $N$  contains a line segment  $I_p \subset \ell_p$  of positive length.

**Corollary 1.9.** *Every  $\mathcal{L}(\mathbb{H})$ -Nikodym set  $N \subset \mathbb{R}^3$  has  $\dim_{\mathbb{H}} N = 3$ .*

It is well known that bounds for Kakeya sets yield bounds for Nikodym sets: we only repeat the standard details below for the reader's convenience. For a similar argument in the case of classical Kakeya and Nikodym sets, see [9, Section 11.3].

*Proof of Corollary 1.9.* We may assume without loss of generality that all the lines  $\ell_p \in \mathcal{L}(\mathbb{H})$  appearing in the definition of 'N' lie in  $\mathcal{L}'(\mathbb{H})$ . Namely, if this is true for a positive measure subset of the points  $p \in \Omega$ , we simply replace  $\Omega$  by that subset. If this fails for Lebesgue almost every point  $p \in \Omega$ , then we apply a rotation  $R$  of, say,  $10^\circ$  around the  $t$ -axis to the objects  $\Omega$ ,  $N$ , and the lines  $\ell_p$ ,  $p \in \Omega$ . Rotations around the  $t$ -axis preserve  $\mathcal{L}(\mathbb{H})$ , and the measure and dimension of  $\Omega$  and  $N$ . After this procedure, we moreover have  $\ell_p \in \mathcal{L}'(\mathbb{H})$  for a.e.  $p \in R(\Omega)$ .

Using Fubini's theorem, start by picking  $y_0 \in \mathbb{R}$  such that  $\mathcal{H}^2(\Omega \cap \mathbb{W}_{y_0}) > 0$ . Here,  $\mathbb{W}_y = \{(x, y, t) : x, t \in \mathbb{R}^3\}$  for  $y \in \mathbb{R}$ . By assumption, for every  $p = (x, y_0, t) \in \Omega \cap \mathbb{W}_{y_0}$ , there exists a line

$$\ell_p := \ell_{(a(p), b(p), c(p))} \in \mathcal{L}'(\mathbb{H})$$

containing  $p$  such that  $N$  contains a line segment  $I_p \subset \ell_p$  of positive length.

Now, note that the map  $(a, b, c) \mapsto \Psi(a, b, c) = (ay_0 + b, y_0, \frac{b}{2}y_0 + c)$  is Lipschitz, and

$$\Omega \cap \mathbb{W}_{y_0} \subset \Psi(\{(a(p), b(p), c(p)) : p \in \Omega \cap \mathbb{W}_{y_0}\}).$$

(This is because the lines  $\ell_p$  contain the points  $p \in \Omega \cap \mathbb{W}_{y_0}$ .) Therefore,

$$\dim_{\mathbb{H}}\{(a(p), b(p), c(p)) : p \in \Omega \cap \mathbb{W}_{y_0}\} \geq \dim_{\mathbb{H}}(\Omega \cap \mathbb{W}_{y_0}) = 2.$$

In particular, the set of lines  $\mathcal{L} := \{\ell_p : p \in \Omega\} \subset \mathcal{L}'(\mathbb{H})$  has  $\dim_{\mathbb{H}} \mathcal{L} \geq 2$  by definition. Therefore, it follows from Theorem 1.5, or to be precise (1.8), that

$$\dim_{\mathbb{H}} N \geq \dim_{\mathbb{H}} \left( \bigcup_{p \in \Omega} I_p \right) = 3.$$

This completes the proof. □

*Remark 1.10.* Nikodym set for 'restricted' families of lines was earlier considered by Kim [6]. Corollary 1.9 answers (a special case of) a question raised on [6, p. 478]. We elaborate on this a little further. The paper [6] considered general families of 2-planes  $p \mapsto \Pi_a(p) \subset \mathbb{R}^3$ , where  $p \mapsto \mathbf{a}(p)$  is a non-vanishing measurable vector field, and

$$p \in \Pi_a(p) \quad \text{and} \quad \text{span}(\mathbf{a}(p)) = \Pi_a(p)^\perp.$$

One can associate Nikodym sets  $N \subset \mathbb{R}^3$  to such a plane family, as follows: for every  $p \in \mathbb{R}^3$ , the requirement is that there exists a line  $\ell_p \subset \mathbb{R}^3$  satisfying

$$p \in \ell_p \subset \Pi_a(p),$$

and a non-trivial segment  $I_p \subset N \cap \ell_p$ . How small can such a Nikodym set  $N \subset \mathbb{R}^3$  be? In [6], Kim approached the question via maximal function estimates, and his results depend on the properties of the vector field  $\mathbf{a}$ . Kim considered vector fields  $\mathbf{a}$  of the form

$$\mathbf{a}(p) = (a_{11}p_1 + a_{21}p_2, a_{12}p_1 + a_{22}p_2, -1), \quad p = (p_1, p_2, p_3) \in \mathbb{R}^3,$$

and defined the ‘discriminant’  $D_{\mathbf{a}} = (a_{12} + a_{21})^2 - 4a_{11}a_{22}$ . In [6, Corollary 1, p. 478], it was shown that the dimension of  $N$  equals 3 if  $D_{\mathbf{a}} \neq 0$ . Right after the corollary, the question is raised, what happens in the situation  $D_{\mathbf{a}} = 0$ .

Now, recall the definition of horizontal lines  $\mathcal{L}(\mathbb{H})$ : these were the lines contained in the planes  $\Pi_p = p * \Pi_0$ , and passing through  $p$ . The planes  $\Pi_p$  fit in the framework of [6], choosing  $\mathbf{a}(p) = (-p_2/2, p_1/2, -1)$ , or  $(a_{11}, a_{12}, a_{21}, a_{22}) = (0, \frac{1}{2}, -\frac{1}{2}, 0)$ . In particular,  $D_{\mathbf{a}} = 0$ . Also, the  $\mathcal{L}(\mathbb{H})$ -Nikodym sets defined above Corollary 1.9 are the same as the Nikodym sets of [6] associated with the planes  $\Pi_p = p * \Pi_0$ . Thus, Corollary 1.9 covers the special case  $(a_{11}, a_{12}, a_{21}, a_{22}) = (0, \frac{1}{2}, -\frac{1}{2}, 0)$  of the problem raised on [6, p. 478].

## 1.2 | Ingredients of the proof

The proof of Theorem 1.5 is based on two ingredients. The first one is a *point-line duality* between horizontal lines and *conical lines* in  $\mathbb{R}^3$ , namely translates of lines contained in the light cone  $\{(x, y, t) : t^2 = x^2 + y^2\}$ . This duality was formalised in our paper [2], although it was already implicit in the work [7] of Liu. Using this point-line duality, Kakeya-type problems for horizontal lines can be transformed into projection problems in  $\mathbb{R}^3$ . These projection problems concern ‘restricted’ families of projections to planes in  $\mathbb{R}^3$ . Sharp results for such families were recently established by Gan, Guo, Guth, Harris, Maldague and Wang [3]. This is the second key component in the proof of Theorem 1.5.

## 2 | PROOFS CONCERNING $SL(2)$ LINES

In this section, we formalise the connection between  $SL(2)$  lines and horizontal lines. We also deduce our main result, Theorem 1.2, from Corollary 1.6.

Recall the  $SL(2)$  lines from Definition 1.1. We write  $\mathcal{L}'_{SL(2)}$  for all the lines in  $\mathcal{L}_{SL(2)}$ , except for the  $x$ -axis, and lines of the form  $L_{\alpha,\beta,\gamma,\delta}$  with  $\delta = 0$ . The difference between  $\mathcal{L}_{SL(2)}$  and  $\mathcal{L}'_{SL(2)}$  is the same as the difference between  $\mathcal{L}(\mathbb{H})$  and  $\mathcal{L}'(\mathbb{H})$ . Consider the map

$$\Xi(x, y, t) := (x, y, t/2).$$

We claim that  $\Xi$  maps the  $SL(2)$  lines to horizontal lines. More precisely:

**Proposition 2.1.** *If  $L_{\alpha,\beta,\gamma,\delta} \in \mathcal{L}'_{SL(2)}$  with  $\delta \neq 0$  and  $\alpha\delta - \beta\gamma = 1$ , then*

$$\Xi(L_{\alpha,\beta,\gamma,\delta}) = \ell_{(a,b,c)} \in \mathcal{L}'(\mathbb{H}), \tag{2.2}$$

where

$$\begin{cases} a = \gamma/\delta, \\ b = 1/\delta, \\ c = -\beta/(2\delta). \end{cases}$$

*Proof.* Fix  $\alpha, \beta, \gamma, \delta$  with  $\delta \neq 0$  and  $\alpha\delta - \beta\gamma = 1$ . Write  $L_{\alpha, \beta, \gamma, \delta}(s) = (\alpha, \beta, 0) + (s\gamma, s\delta, s)$ . It is a straightforward computation to check that

$$\Xi(L_{\alpha, \beta, \gamma, \delta}(s)) = \ell_{(a, b, c)}(\beta + s\delta), \quad s \in \mathbb{R}.$$

Since  $\delta \neq 0$  by assumption, this completes the proof.  $\square$

We are then prepared to prove Theorem 1.2.

*Proof of Theorem 1.2.* We may assume that  $\mathcal{L} \subset \mathcal{L}'_{SL(2)}$ , since the directions of the lines in  $\mathcal{L}_{SL(2)} \setminus \mathcal{L}'_{SL(2)}$  are contained in the  $\mathcal{H}^2$  null set  $S^2 \cap \{(x, 0, t) : x, t \in \mathbb{R}\}$ . Similarly, we may assume that  $\mathcal{L}$  contains no lines in the  $xy$ -plane; thus, every  $L \in \mathcal{L}$  has the form  $L = L_{\alpha, \beta, \gamma, \delta}$  for some  $\alpha, \beta, \gamma, \delta$  with  $\delta \neq 0$  and  $\alpha\delta - \beta\gamma = 1$ .

Since  $\mathcal{L} \subset \mathcal{L}'_{SL(2)}$ , we infer from Proposition 2.1 that  $\Xi(\mathcal{L}) := \{\Xi(\ell) : \ell \in \mathcal{L}\} \subset \mathcal{L}'(\mathbb{H})$ . We claim that

$$\mathcal{H}^2(\text{dir}(\Xi(\mathcal{L}))) > 0. \quad (2.3)$$

According to Corollary 1.6, this will imply that

$$\dim_{\mathbb{H}}(\cup \mathcal{L}) = \dim_{\mathbb{H}} \Xi(\cup \mathcal{L}) = \dim_{\mathbb{H}}(\cup \Xi(\mathcal{L})) = 3,$$

and complete the proof.

To verify (2.3), fix  $L = L_{\alpha, \beta, \gamma, \delta} \in \mathcal{L}$ . Then, by (2.2), we have  $\Xi(L) = \ell_{(a, b, c)}$  with

$$\begin{cases} a = \gamma/\delta, \\ b = 1/\delta \\ c = -\beta/(2\delta). \end{cases}$$

We will use this information in the form of the following inclusion: writing  $F(\gamma, \delta) := (\gamma/\delta, 1/\delta)$ , we have

$$\{(a, b) \in \mathbb{R}^2 : \ell_{(a, b, c)} \in \Xi(\mathcal{L})\} \supset \{F(\gamma, \delta) : L_{\alpha, \beta, \gamma, \delta} \in \mathcal{L}\}. \quad (2.4)$$

Since  $\mathcal{H}^2(\text{dir}(\mathcal{L})) > 0$ , and the direction of  $L_{\alpha, \beta, \gamma, \delta} = (\alpha, \beta, 0) + \text{span}(\gamma, \delta, 1)$  is determined by  $\gamma$  and  $\delta$ , we know that

$$\mathcal{H}^2(\{(\gamma, \delta) \in \mathbb{R}^2 : L_{\alpha, \beta, \gamma, \delta} \in \mathcal{L}\}) > 0.$$

It now follows from (2.4), and the fact that  $F$  is locally bilipschitz in the set  $\mathbb{R}^2 \setminus \{(\gamma, \delta) : \delta = 0\}$  (since  $|\det DF(\gamma, \delta)| = 1/\delta^3$ ), that also

$$\mathcal{H}^2(\{(a, b) \in \mathbb{R}^2 : \ell_{(a,b,c)} \in \Xi(\mathcal{L})\}) \geq \mathcal{H}^2(\{F(\gamma, \delta) : L_{\alpha,\beta,\gamma,\delta} \in \mathcal{L}\}) > 0.$$

Since the direction of  $\ell_{(a,b,c)} = (b, 0, c) + \text{span}(a, 1, b/2)$  is determined by  $(a, b)$ , we may now infer that  $\mathcal{H}^2(\text{dir}(\Xi(\mathcal{L}))) > 0$ , as claimed in (2.3). □

### 3 | PROOFS CONCERNING HORIZONTAL LINES

We start by proving Theorem 1.5.

*Proof of Theorem 1.5.* Without loss of generality, we may assume that  $\mathcal{L} = \ell(P)$  is a Borel set of lines, that is,  $P \subset \mathbb{R}^3$  is a Borel set. For the full details of this reduction, see [7, Section 3] or [1, Theorem 7.9]. The idea is that we can first replace  $\cup \mathcal{L}$  by a  $G_\delta$ -set  $G \supset \cup \mathcal{L}$  without affecting  $\dim_{\mathbb{H}}(\cup \mathcal{L})$ . Then, it is easy to check that the set of parameters  $P' := \{p \in \mathbb{R}^3 : \ell(p) \subset G\}$  is a Borel set with  $P' \supset P$ , in particular  $\dim_{\mathbb{H}} P' \geq \dim_{\mathbb{H}} P$ . Finally, writing  $\mathcal{L}' := \ell(P')$ , we have

$$\dim_{\mathbb{H}}(\cup \mathcal{L}) = \dim_{\mathbb{H}} G \geq \dim_{\mathbb{H}}(\cup \mathcal{L}').$$

So, if the result is known for Borel sets of lines, it follows for  $\mathcal{L}$ .

Write  $\mathcal{L} := \ell(P)$ , where  $P \subset \mathbb{R}^3$  is Borel. Write also

$$K_y := \left\{ \left( ay + b, \frac{b}{2}y + c \right) : (a, b, c) \in P \right\}, \quad y \in \mathbb{R},$$

and note that  $K_y$  is a ‘slice’ of  $\cup \mathcal{L}$  with the plane  $\mathbb{W}_y := \{(x, y, t) : x, t \in \mathbb{R}\}$ :

$$(\cup \mathcal{L}) \cap \mathbb{W}_y \cong K_y,$$

where ‘ $\cong$ ’ refers to the isometry  $\iota_y : \mathbb{R}^2 \rightarrow \mathbb{W}_y$ , defined by  $\iota_y(x, t) = (x, y, t)$ . In order to prove that

$$\dim_{\mathbb{H}}(\cup \mathcal{L}) \geq \min\{\dim_{\mathbb{H}} \mathcal{L} + 1, 3\}, \tag{3.1}$$

we now claim that

$$\dim_{\mathbb{H}} K_y = \min\{\dim_{\mathbb{H}} P, 2\} \quad \text{for a.e. } y \in \mathbb{R}. \tag{3.2}$$

If  $\mathcal{L}$  consisted of line segments of positive length, and not full lines, then we would have to modify (3.2) as follows: for every  $\epsilon > 0$ , there exists an interval  $I \subset \mathbb{R}$  of positive length such that  $\dim_{\mathbb{H}} K_y \geq \min\{\dim_{\mathbb{H}} P - \epsilon, 2\}$  for a.e.  $y \in I$ . This interval would (be chosen to) consist of points  $y \in \mathbb{R}$  with the property that the plane  $\mathbb{W}_y$  intersects a family of segments corresponding to a  $(\dim_{\mathbb{H}} P - \epsilon)$ -dimensional Borel subset  $P' \subset P$ . We refer the reader to [7, Section 3] for a very similar argument.



Clearly, (3.1) follows from (3.2) by the ‘Fubini inequality’ for Hausdorff measures (hence dimension), see [1, Theorem 5.8] or [8, Theorem 7.7]. To prove (3.2), we define

$$v(y) := (y, 1, 0) \quad \text{and} \quad w(y) := (0, y/2, 1), \quad y \in \mathbb{R}.$$

Then, we note that for  $y \in \mathbb{R}$  fixed,  $K_y$  can be expressed as

$$\begin{aligned} K_y &= \{(\langle p, v(y) \rangle, \langle p, w(y) \rangle) : p \in P\} \\ &= \{(\langle \pi_{V_y}(p), v(y) \rangle, \langle \pi_{V_y}(p), w(y) \rangle) : p \in P\}, \end{aligned} \quad (3.3)$$

where ‘ $\langle \cdot, \cdot \rangle$ ’ is the Euclidean dot product and  $\pi_{V_y}$  the Euclidean orthogonal projection from  $\mathbb{R}^3$  onto the plane

$$V_y := \text{span}(\{v(y), w(y)\}).$$

It is then easy to see that

$$\dim_{\mathbb{H}} K_y = \dim_{\mathbb{H}} \pi_{V_y}(P), \quad y \in \mathbb{R}. \quad (3.4)$$

Indeed, expression (3.3) shows that  $K_y$  can be written as the image of  $\pi_{V_y}(P)$  under the linear map

$$M_y : V_y \rightarrow \mathbb{R}^2, \quad M_y(q) = (\langle q, v(y) \rangle, \langle q, w(y) \rangle),$$

and thus,  $\dim_{\mathbb{H}} K_y = \dim_{\mathbb{H}} M_y(\pi_{V_y}(P))$ . Moreover,  $\dim_{\mathbb{H}} M_y(\pi_{V_y}(P)) = \dim_{\mathbb{H}} \pi_{V_y}(P)$  holds as the linear map  $M_y$  is invertible by the linear independence of  $v(y)$  and  $w(y)$ . Hence, (3.4) holds as desired.

To complete the proof, we claim that

$$\dim_{\mathbb{H}} \pi_{V_y}(P) = \min\{\dim_{\mathbb{H}} P, 2\} \quad \text{for a.e. } y \in \mathbb{R}. \quad (3.5)$$

The idea is that  $\{\pi_{V_y}\}_{y \in \mathbb{R}}$  is a one-parameter family of orthogonal projections to planes in  $\mathbb{R}^3$  which satisfies the hypotheses of [3, Corollary 1].

Which planes are the planes  $V_y$ ? Note that

$$v(y) \times w(y) = (1, -y, y^2/2) =: e_y.$$

Thus,  $V_y = e_y^\perp$ . Moreover, the lines  $\ell_y := \text{span}(e_y)$  are all contained in a  $45^\circ$  rotated copy of the light cone

$$C := \{(x, y, t) \in \mathbb{R}^3 : t^2 = x^2 + y^2\},$$

see [2, Section 2.2] for the details. This implies that the projections  $\{\pi_{V_y}\}_{y \in \mathbb{R}}$  satisfy the curvature condition [3, (1)]. In fact, up to the rotation by  $45^\circ$ , this family of projections is precisely the ‘model

example' mentioned just below [3, (1)]. Therefore, (3.5) follows from [3, Corollary 1], and the proof is complete.  $\square$

We conclude the paper by proving Corollary 1.6.

*Proof of Corollary 1.6.* Firstly, note that  $\mathcal{H}^2(\text{dir}(\mathcal{L} \cap \mathcal{L}'(\mathbb{H}))) > 0$ . This is because  $\text{dir}(\mathcal{L}'(\mathbb{H}))$  contains all the directions on  $S^2$ , except for those contained in the null set  $\{(x, 0, t) : x, t \in \mathbb{R}\}$ . Therefore, we may assume that  $\mathcal{L} \subset \mathcal{L}'(\mathbb{H})$ .

Write  $\mathcal{L} = \ell(P)$ , where  $P \subset \mathbb{R}^3$ . Recall that

$$\begin{aligned} \mathcal{L} = \ell(P) &= \left\{ \left( as + b, s, \frac{b}{2}s + c \right) : s \in \mathbb{R}, (a, b, c) \in P \right\} \\ &= \left\{ (b, 0, c) + \text{span} \left( a, 1, \frac{b}{2} \right) : (a, b, c) \in P \right\}. \end{aligned}$$

Since  $\mathcal{H}^2(\text{dir}(\mathcal{L})) > 0$  by assumption, we see that

$$\mathcal{H}^2 \left( \left\{ \left( a, \frac{b}{2} \right) : (a, b, c) \in P \right\} \right) > 0,$$

and consequently,  $\dim_{\mathbb{H}} P \geq 2$ . The claim now follows from Theorem 1.5.  $\square$

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