

This is a self-archived version of an original article. This version may differ from the original in pagination and typographic details.

Author(s): Paternain, Gabriel P.; Salo, Mikko

Title: A sharp stability estimate for tensor tomography in non-positive curvature

Year: 2021

Version: Published version

Copyright: © The Author(s) 2020

Rights: CC BY 4.0

Rights url: <https://creativecommons.org/licenses/by/4.0/>

Please cite the original version:

Paternain, G. P., & Salo, M. (2021). A sharp stability estimate for tensor tomography in non-positive curvature. *Mathematische Zeitschrift*, 298(3-4), 1323-1344.

<https://doi.org/10.1007/s00209-020-02638-x>



A sharp stability estimate for tensor tomography in non-positive curvature

Gabriel P. Paternain¹ · Mikko Salo²

Received: 18 January 2020 / Accepted: 16 September 2020
© The Author(s) 2020

Abstract

We consider the geodesic X-ray transform acting on solenoidal tensor fields on a compact simply connected manifold with strictly convex boundary and non-positive curvature. We establish a stability estimate of the form $L^2 \mapsto H_T^{1/2}$, where the $H_T^{1/2}$ -space is defined using the natural parametrization of geodesics as initial boundary points and incoming directions (fan-beam geometry); only tangential derivatives at the boundary are used. The proof is based on the Pestov identity with boundary term localized in frequency.

1 Introduction

To motivate our results, let us begin with the simplest case of the Radon transform in \mathbb{R}^2 in parallel beam geometry (see [15] for more details).

Example If $f \in C_c^\infty(\mathbb{R}^2)$, the Radon transform of f is

$$Rf(s, v) = \int_{-\infty}^{\infty} f(sv + tv^\perp) dt, \quad s \in \mathbb{R}, v \in S^1,$$

where v^\perp is the rotation of v by 90° counterclockwise. The Fourier transform of Rf in the s variable, denoted by $(Rf)^\sim(\cdot, v)$, satisfies the *Fourier slice theorem*

$$(Rf)^\sim(\sigma, v) = (2\pi)^{1/2} \hat{f}(\sigma v), \quad \sigma \in \mathbb{R}, v \in S^1.$$

✉ Gabriel P. Paternain
g.p.paternain@dpms.cam.ac.uk
Mikko Salo
mikko.j.salo@jyu.fi

¹ Department of Pure Mathematics and Mathematical Statistics, University of Cambridge, Cambridge CB3 0WB, UK

² Department of Mathematics and Statistics, University of Jyväskylä, Jyväskylä, Finland

Using the Plancherel theorem and polar coordinates, we obtain that

$$\begin{aligned} \|f\|_{L^2(\mathbb{R}^2)}^2 &= \|\hat{f}\|_{L^2(\mathbb{R}^2)}^2 = \int_0^\infty \int_{S^1} |\hat{f}(\sigma v)|^2 \sigma \, dv \, d\sigma \\ &= \frac{1}{2} \int_{-\infty}^\infty \int_{S^1} |\hat{f}(\sigma v)|^2 |\sigma| \, dv \, d\sigma \\ &= \frac{1}{4\pi} \int_{-\infty}^\infty \int_{S^1} |(Rf)^\sim(\sigma, v)|^2 |\sigma| \, dv \, d\sigma. \end{aligned}$$

In particular, this implies the stability estimate

$$\|f\|_{L^2(\mathbb{R}^2)} \leq \frac{1}{(4\pi)^{1/2}} \|Rf\|_{H_T^{1/2}(\mathbb{R} \times S^1)} \tag{1.1}$$

with the mixed Sobolev norm $\|h\|_{H_T^{1/2}(\mathbb{R} \times S^1)} = \|(1 + \sigma^2)^{1/4} \tilde{h}(\sigma, v)\|_{L^2(\mathbb{R} \times S^1)}$.

The main question we address in the present paper is the existence of a stability estimate analogous to (1.1) but in a geometric setting, namely, when \mathbb{R}^2 and the lines in the plane are replaced by a Riemannian manifold and its geodesics. There are two features we wish to preserve from (1.1): one is its $L^2 \rightarrow H^{1/2}$ nature and the other is that the $H_T^{1/2}$ only incorporates “half of the derivatives” of the target space (space of geodesics).

Let us first be more precise about the geometric setting. The geodesic X-ray transform acts on functions defined on the unit sphere bundle of a compact oriented d -dimensional Riemannian manifold (M, g) with smooth boundary ∂M ($d \geq 2$). Let SM denote the unit sphere bundle on M , i.e.

$$SM := \{(x, v) \in TM : |v|_g = 1\}.$$

We define the volume form on SM by $d\Sigma^{2d-1}(x, v) = dV^d(x) \wedge dS_x(v)$, where dV^d is the volume form on M and dS_x is the volume form on the fibre $S_x M$. The boundary of SM is $\partial SM := \{(x, v) \in SM : x \in \partial M\}$. On ∂SM the natural volume form is $d\Sigma^{2d-2}(x, v) = dV^{d-1}(x) \wedge dS_x(v)$, where dV^{d-1} is the volume form on ∂M . We distinguish two subsets of ∂SM (incoming and outgoing directions)

$$\partial_\pm SM := \{(x, v) \in \partial SM : \pm \langle v, \nu(x) \rangle_g \leq 0\},$$

where $\nu(x)$ is the outward unit normal vector on ∂M at x . It is easy to see that

$$\partial_+ SM \cap \partial_- SM = S(\partial M).$$

Given $(x, v) \in SM$, we denote by $\gamma_{x,v}$ the unique geodesic with $\gamma_{x,v}(0) = x$ and $\dot{\gamma}_{x,v}(0) = v$ and let $\tau(x, v)$ be the first time when the geodesic $\gamma_{x,v}$ exits M .

We say that (M, g) is *non-trapping* if $\tau(x, v) < \infty$ for all $(x, v) \in SM$. In this case the space of geodesics is naturally parametrized by $\partial_+ SM$ (fan-beam geometry).

Definition 1.1 The *geodesic X-ray transform* of a function $F \in C^\infty(SM)$ is the function

$$IF(x, v) := \int_0^{\tau(x,v)} F(\gamma_{x,v}(t), \dot{\gamma}_{x,v}(t)) \, dt, \quad (x, v) \in \partial_+ SM.$$

If the manifold (M, g) is non-trapping and has strictly convex boundary, then $\tau \in C^\infty(\partial_+ SM)$ and as a consequence $I : C^\infty(SM) \rightarrow C^\infty(\partial_+ SM)$. Moreover, I extends

as a bounded operator $I : H^k(SM) \rightarrow H^k(\partial_+ SM)$ for all $k \geq 0$ [23, Theorem 4.2.1], where the Sobolev spaces are defined using the L^2 -inner products arising from the volume forms introduced above.

We shall consider I acting on special functions $F \in C^\infty(SM)$ induced by symmetric tensor fields. We denote by $C^\infty(S^m(T^*M))$ the space of smooth covariant symmetric tensor fields of rank m on M with L^2 inner product:

$$(u, w) := \int_M u_{i_1 \dots i_m} w^{i_1 \dots i_m} dV^d,$$

where $w^{i_1 \dots i_m} = g^{i_1 j_1} \dots g^{i_m j_m} w_{j_1 \dots j_m}$. There is a natural map

$$\ell_m : C^\infty(S^m(T^*M)) \rightarrow C^\infty(SM)$$

given by $\ell_m(f)(x, v) := f_x(v, \dots, v)$. We can now define the geodesic ray transform acting on symmetric m -tensors simply by setting $I_m := I \circ \ell_m$. Let $d^s = \sigma \nabla$ be the symmetric inner differentiation, where ∇ is the Levi-Civita connection associated with g , and σ denotes symmetrization. It is easy to check that if $f = d^s p$ for some $p \in C^\infty(S^{m-1}(T^*M))$ with $p|_{\partial M} = 0$, then $I_m f = 0$. The tensor tomography problem asks the following question: are such tensors the only obstructions for I_m to be injective? If this is the case, then we say I_m is *solenoidal injective* or *s-injective* for short. This terminology is explained by the following well known decomposition (cf. [23]). Given $f \in H^k(S^m(T^*M))$, $k \geq 0$, there exist uniquely determined $f_s \in H^k(S^m(T^*M))$ and $p \in H^{k+1}(S^{m-1}(T^*M))$, such that

$$f = f_s + d^s p, \quad \delta^s f_s = 0, \quad p|_{\partial M} = 0,$$

where δ^s is the divergence. We call f_s and $d^s p$ the *solenoidal* part and *potential* part of f respectively.

There is one important instance in which the tensor tomography problem is solved for tensors of any order m and in any dimension d . This is when we assume in addition that the sectional curvature of M is non-positive. Moreover, in this case a stability estimate is available as follows:

Theorem 1.2 ([21] and [23, Theorem 4.3.3]) *Let (M, g) be a simply connected compact manifold with strictly convex boundary and non-positive sectional curvature. Given $m \geq 0$ there is a constant $C > 0$ such that for any $f \in H^1(S^m(T^*M))$*

$$\|f_s\|_{L^2}^2 \leq C(\|I_m f\|_{H^1(\partial_+ SM)}^2 + m\|f\|_{H^1}\|I_m f\|_{L^2}).$$

(We note that a manifold as in the theorem is necessarily non-trapping.) There are two notorious differences between the stability estimate above and that in (1.1). Firstly, the stability estimate in Theorem 1.2 has in the right hand side the term $\|f\|_{H^1}\|I_m f\|_{L^2}$ when $m \neq 0$. Secondly, it is not sharp in the sense that it is $L^2 \rightarrow H^1$. In [3] Boman and Sharafutdinov resolved these issues for strictly convex domains in Euclidean space and asked whether the same was true for the more general setting of non-positively curved Riemannian manifolds. This paper provides a positive answer to these questions. Moreover, the 1/2-Sobolev space on the target space of I_m is naturally suggested by the geometry and the most relevant L^2 -energy identity for the problem: *the Pestov identity*. The Pestov identity with boundary term in the way that we shall use it here was derived for instance in [10, Lemma 8]. It contains a boundary term given by

$$(Tu, \overset{\vee}{\nabla} u)_{L^2(\partial SM)} \tag{1.2}$$

where $u \in C^\infty(\partial SM)$, $\overset{v}{\nabla}$ is the vertical gradient, and T is a *tangential operator* defined by

$$Tu := \langle v(x), v \rangle \overset{h}{\nabla} u - vXu,$$

where X is the geodesic vector field and $\overset{h}{\nabla}$ the full horizontal gradient (we refer to Sects. 2 and 3 for the precise definitions). The operator T acts on ∂SM and it only involves horizontal derivatives. This suggests that only horizontal derivatives of $I_m f$ on ∂SM should appear in the stability estimate.

We can define the *tangential* (or *horizontal*) $H^1(\partial SM)$ -norm by setting

$$\|u\|_{H^1_T(\partial SM)}^2 := \|u\|_{L^2(\partial SM)}^2 + \|\overset{h}{\nabla} u\|_{L^2(\partial SM)}^2$$

where $\overset{h}{\nabla} u$ contains the tangential derivatives in $\overset{h}{\nabla} u$ along ∂M . For example, if M is a ball in \mathbb{R}^d with Euclidean metric, then $\partial SM = \partial M \times S^{d-1}$ and

$$\|u\|_{H^1_T(\partial SM)}^2 = \int_{\partial M} \int_{S^{d-1}} (|u(x, v)|^2 + |\nabla_x u(x, v)|^2) dS(v) dV(x)$$

where ∇_x is the gradient on ∂M . The space $H^1_T(\partial_+ SM)$ is defined by restriction, and $H^{1/2}_T(\partial_+ SM)$ is defined by complex interpolation between $L^2(\partial_+ SM)$ and $H^1_T(\partial_+ SM)$.

With this definition we may now state our main result:

Theorem 1.3 *Let (M, g) be a simply connected compact manifold with strictly convex boundary and non-positive sectional curvature. Given $m \geq 0$ there is a constant $C > 0$ such that for any $f \in H^1(S^m(T^*M))$*

$$\|f_S\|_{L^2} \leq C \|I_m f\|_{H^{1/2}_T(\partial_+ SM)}.$$

The constant C can be estimated in terms of m and (M, g) . In fact, for the related stability result for the transport equation in Theorem 5.1, one can take $C = 1$.

Most of work in the proof of Theorem 1.3 lies in the upgrade from the $H^1(\partial_+ SM)$ -norm in Theorem 1.2 to the $H^{1/2}_T(\partial_+ SM)$ -norm. The upgrade is possible thanks to the localization in frequency of the Pestov identity first noted in full generality in [17] (in two dimensions this was proved in [19]). However, in [17] we did not consider the boundary term. It turns out, quite remarkably, that the boundary term (1.2) also localizes in frequency. This allows us to change the norm for $I_m f$ from H^1 to $H^{1/2}_T$, thus producing the upgrade. We also mention that for $d = 2$ the proof would simplify substantially because spherical harmonics decompositions and the T operator are simpler; the two-dimensional proof will be given in [20].

1.1 Related results and alternative approaches

There are many earlier results on stability estimates for I_m , using different techniques. One approach is to consider the normal operator $I_m^* I_m$ where the adjoint I_m^* is computed using a natural L^2_μ -inner product on $\partial_+ SM$ suggested by the Santaló formula. When M is free of conjugate points, it turns out that $I_m^* I_m$ is an (elliptic) Ψ DO of order -1 on a slightly larger open manifold engulfing M . This approach has produced stability estimates for the normal operator, cf. [26], and has proved to be of fundamental importance in the solution of several

geometric inverse problems. One drawback is that one needs to work on the slightly extended manifold, unless one is willing to incorporate modified transmission conditions to account for boundary effects [14]. Another drawback is that the approach does not give estimates for the constants due to a compactness argument. Still, quite recently, a sharp stability estimate has been obtained in [1], by defining a suitable $H^{1/2}$ -norm based on this extension or equivalently on a different parametrization of the space of geodesics. Our approach in Theorem 1.3 deals directly with the boundary and with the space of geodesics in “fan-beam” geometry as given by $\partial_+ SM$. In this sense our theorem addresses the open problem stated at the end of the introduction in [1]. Also our tangential derivatives are naturally suggested by the geometry of the problem.

The microlocal approach can actually be pushed further, using scattering calculus and a combination of a local theorem with a global strict convexity assumption as in [27,28]. This is also very powerful, and allows even to consider situations with conjugate points as long as $d \geq 3$. However, the stability estimates thus produced are $L^2 \rightarrow H^1$.

One drawback of Theorem 1.3 is the curvature assumption. In [1] the estimates hold for compact simple manifolds for $m = 0, 1$ and for $m = 2$ when I_m is known to be injective, e.g. when $d = 2$ [18,25]. Another possible improvement would be to replace the assumption $f \in H^1$ by $f \in L^2$ and to prove the two-sided inequality

$$c \|f_s\|_{L^2} \leq \|I_m f\|_{H_T^{1/2}(\partial_+ SM)} \leq C \|f_s\|_{L^2}.$$

For this, one would like to prove that I_m is bounded from L^2 to $H_T^{1/2}$. This is true if f vanishes near ∂M since I_m is a Fourier integral operator, but it is not clear how to prove this with uniform bounds when the support of f extends up to ∂M .

Finally, we mention that quite recently, Monard [13] has studied very detailed mapping properties of I_0 for 2D discs of constant curvature at all Sobolev scales; for these cases, he also obtains a stability estimate with a suitable $H^{1/2}$ -norm. Further references to stability estimates for I_m may be found in [1].

It is natural to speculate whether Theorem 1.3 extends to more general situations. For example one could try to relax the assumption about strict convexity of the boundary as in [7] or allow for some hyperbolic trapping as in [6]. One could also speculate on extensions that include attenuations and sections of a suitable vector bundle. We do not pursue these here.

2 Geometric preliminaries

In this section we collect some geometric preliminaries for subsequent use.

Unit sphere bundle We start by recalling some standard notions related to the geometry of the unit sphere bundle. We follow the setup and notation of [19]; for other approaches and background information see [5,8,11,16,23].

Let (M, g) be a d -dimensional compact Riemannian manifold with or without boundary, having unit sphere bundle $\pi : SM \rightarrow M$, and let X be the geodesic vector field. We equip SM with the Sasaki metric. If \mathcal{V} denotes the vertical subbundle given by $\mathcal{V} = \text{Ker } d\pi$, then there is an orthogonal splitting with respect to the Sasaki metric:

$$TSM = \mathbb{R}X \oplus \mathcal{H} \oplus \mathcal{V}. \tag{2.1}$$

The subbundle \mathcal{H} is called the horizontal subbundle. Elements in $\mathcal{H}(x, v)$ and $\mathcal{V}(x, v)$ are canonically identified with elements in the codimension one subspace $\{v\}^\perp \subset T_x M$ by the

isomorphisms

$$d\pi_{x,v} : \mathcal{V}(x, v) \rightarrow \{v\}^\perp, \quad \mathcal{K}_{x,v} : \mathcal{H}(x, v) \rightarrow \{v\}^\perp,$$

here $\mathcal{K}_{x,v}$ is the connection map coming from Levi–Civita connection. We will use these identifications freely below.

We shall denote by \mathcal{Z} the set of smooth functions $Z : SM \rightarrow TM$ such that $Z(x, v) \in T_x M$ and $\langle Z(x, v), v \rangle = 0$ for all $(x, v) \in SM$. Alternatively we may describe the elements of \mathcal{Z} as follows. Consider the pull-back bundle π^*TM over SM and let N denote the subbundle of π^*TM whose fiber over (x, v) is given by $N_{(x,v)} = \{v\}^\perp$. Then \mathcal{Z} coincides with the smooth sections of the bundle N . Note that N carries a natural scalar product and thus an L^2 -inner product (using the Liouville measure on SM for integration).

Given a smooth function $u \in C^\infty(SM)$ we can consider its gradient ∇u with respect to the Sasaki metric. Using the splitting above we may write uniquely in the decomposition (2.1)

$$\nabla u = ((Xu)X, \overset{h}{\nabla} u, \overset{v}{\nabla} u).$$

The derivatives $\overset{h}{\nabla} u \in \mathcal{Z}$ and $\overset{v}{\nabla} u \in \mathcal{Z}$ are called horizontal and vertical derivatives respectively. (This differs from the definitions in [11,23] since here all objects are defined on SM as opposed to TM .)

The geodesic vector X acts on \mathcal{Z} as follows:

$$XZ(x, v) := \frac{DZ(\varphi_t(x, v))}{dt} \Big|_{t=0} \tag{2.2}$$

where D/dt is the covariant derivative with respect to Levi–Civita connection and φ_t is the geodesic flow. With respect to the L^2 -product on N , the formal adjoints of $\overset{v}{\nabla} : C^\infty(SM) \rightarrow \mathcal{Z}$ and $\overset{h}{\nabla} : C^\infty(SM) \rightarrow \mathcal{Z}$ are denoted by $-\text{div}$ and $-\overset{h}{\text{div}}$ respectively. Note that since X leaves invariant the volume form of the Sasaki metric we have $X^* = -X$ for both actions of X on $C^\infty(SM)$ and \mathcal{Z} .

Let $R(x, v) : \{v\}^\perp \rightarrow \{v\}^\perp$ be the operator determined by the Riemann curvature tensor by $R(x, v)w = R(w, v)v$, and let $d = \dim M$.

Spherical harmonics decomposition There is a natural spherical harmonics decomposition with respect to the vertical Laplacian $\Delta = -\text{div} \overset{v}{\nabla}$ (cf. [19, Section 3] and [8]):

$$L^2(SM) = \bigoplus_{m=0}^\infty H_m(SM),$$

so that any $f \in L^2(SM)$ has the orthogonal decomposition

$$f = \sum_{m=0}^\infty f_m.$$

We write $\Omega_m = H_m(SM) \cap C^\infty(SM)$. Then $\Delta u = m(m + d - 2)u$ for $u \in \Omega_m$ and we let $\lambda_m := m(m + d - 2)$.

Decomposition of X The geodesic vector field has a special behaviour with respect to the decomposition into fibrewise spherical harmonics: it maps Ω_m into $\Omega_{m-1} \oplus \Omega_{m+1}$ [8, Proposition 3.2]. Hence on Ω_m we can write

$$X = X_- + X_+$$

where $X_- : \Omega_m \rightarrow \Omega_{m-1}$ and $X_+ : \Omega_m \rightarrow \Omega_{m+1}$. By [8, Proposition 3.7] the operator X_+ is overdetermined elliptic (i.e. it has injective principal symbol). We can explain the decomposition $X = X_- + X_+$ as follows. Fix $x \in M$ and consider local coordinates which are geodesic at x (so $\partial_{x_j} g_{kl}(x) = 0$ for all j, k, l). Then $Xu(x, v) = v^i \frac{\partial u}{\partial x^i}$. We now use the following basic fact about spherical harmonics: the product of a spherical harmonic of degree m with a spherical harmonic of degree one decomposes as the sum of spherical harmonics of degree $m - 1$ and $m + 1$.

3 Pestov identity with boundary term

We recall the following commutator formulas from [19]:

$$\begin{aligned} [X, \overset{v}{\nabla}] &= -\overset{h}{\nabla}, \\ [X, \overset{h}{\nabla}] &= R\overset{v}{\nabla}, \\ \overset{h}{\text{div}}\overset{v}{\nabla} - \overset{v}{\text{div}}\overset{h}{\nabla} &= (d - 1)X. \end{aligned} \tag{3.1}$$

Taking adjoints gives the following commutator formulas on \mathcal{Z} :

$$\begin{aligned} [X, \overset{v}{\text{div}}] &= -\overset{h}{\text{div}}, \\ [X, \overset{h}{\text{div}}] &= -\overset{v}{\text{div}}R. \end{aligned} \tag{3.2}$$

Using these relations one can establish a Pestov identity with boundary term. Let $\mu(x, v) := \langle v, v(x) \rangle$. We let $\|\cdot\|$ and (\cdot, \cdot) denote the L^2 -norm and L^2 -inner product respectively determined by the volume form $d\Sigma^{2d-1}$ on SM ; we let $(\cdot, \cdot)_{\partial SM}$ stand for the L^2 -inner product on ∂SM determined by $d\Sigma^{2d-2}$.

Proposition 3.1 (Pestov identity with boundary term, cf. Lemma 8 in [10]) *Let (M, g) be a compact manifold with smooth boundary. If $u \in C^\infty(SM)$, then*

$$\|\overset{v}{\nabla}Xu\|^2 = \|X\overset{v}{\nabla}u\|^2 - (R\overset{v}{\nabla}u, \overset{v}{\nabla}u) + (d - 1)\|Xu\|^2 + P(u, u),$$

where P is the quadratic form defined by

$$P(u, w) = (Tu, \overset{v}{\nabla}w)_{\partial SM},$$

and $Tu := \mu \overset{h}{\nabla}u - Xu\overset{v}{\nabla}\mu$.

We can express T using the full horizontal derivative $\overset{h}{\nabla}u = \overset{h}{\nabla}u + (Xu)v$ as $Tu = \mu \overset{h}{\nabla}u - vXu$ since $\overset{v}{\nabla}\mu = v - \mu v$. It turns out that T can also be rewritten in such a way that it acts on functions $u \in C^\infty(\partial SM)$. To see this, consider the operators

$$\nabla^\parallel u := \nabla u - \langle \nabla u, (v, 0) \rangle (v, 0) \tag{3.3}$$

and

$$X^\parallel := X - \langle X, (v, 0) \rangle (v, 0) = (v - \langle v, v \rangle v, 0) = (v^\parallel, 0) \tag{3.4}$$

at the boundary. Note that $(\nu, 0)$ is the horizontal lift of ν . We also define the horizontal part of ∇^{\parallel} as

$$\overset{h}{\nabla}^{\parallel} u := d\pi(\nabla^{\parallel} u) = \overset{h}{\nabla} u - \langle \overset{h}{\nabla} u, \nu \rangle \nu.$$

The following simple lemma is proved in [10, Lemma 14]:

Lemma 3.2 *We have*

$$Tu = \mu \overset{h}{\nabla}^{\parallel} u - \nu X^{\parallel} u. \tag{3.5}$$

From this form we can clearly see that $T : C^{\infty}(\partial SM) \rightarrow \mathcal{Z}|_{\partial SM}$.

Remark 3.3 In 2D, $Tu = (\mathbb{T}u)iv$, where \mathbb{T} is the tangential horizontal vector field $(iv, 0)$ and i is the complex structure of the surface. The vector field \mathbb{T} and the vertical vector field V form a commuting frame for ∂SM .

We next rewrite the Pestov identity in terms of X_+ and X_- as in [17]. To do this, we need some notation: for a polynomially bounded sequence $\alpha = (\alpha_l)_{l=0}^{\infty}$ of real numbers, we define a corresponding "inner product"

$$(u, w)_{\alpha} = \sum_{l=0}^{\infty} \alpha_l (u_l, w_l)_{L^2(SM)}, \quad u, w \in C^{\infty}(SM).$$

We also write $\|u\|_{\alpha}^2 = \sum_{l=0}^{\infty} \alpha_l \|u_l\|^2$. (If each α_l is positive one gets an actual inner product and norm, but it is notationally convenient to allow zero or negative α_l .)

The Pestov identity can then be written in the following form. Define

$$\alpha_l = \lambda_l \left[\left(1 + \frac{1}{l+d-2} \right)^2 - 1 \right] + (d-1), \tag{3.6}$$

$$\beta_l = \lambda_l \left[1 - \left(1 - \frac{1}{l} \right)^2 \right] - (d-1). \tag{3.7}$$

The next result extends [17, Proposition 4.4] to the case with boundary terms.

Proposition 3.4 (Pestov identity in terms of X_{\pm} with boundary term) *Let (M, g) be a compact manifold with smooth boundary. If $u \in C^{\infty}(SM)$, then*

$$\|X_- u\|_{\alpha}^2 - (R \overset{\vee}{\nabla} u, \overset{\vee}{\nabla} u) + \|Z(u)\|^2 + P(u, u) = \|X_+ u\|_{\beta}^2,$$

where $Z(u)$ is $\overset{\vee}{\text{div}}$ -free.

Proof Recall from [19, Lemma 4.4] that

$$\overset{h}{\nabla} u = \overset{\vee}{\nabla} \left[\sum_{l=1}^{\infty} \left(\frac{1}{l} X_{+u_{l-1}} - \frac{1}{l+d-2} X_{-u_{l+1}} \right) \right] + Z(u) \tag{3.8}$$

where $Z(u) \in \mathcal{Z}$ satisfies $\overset{\vee}{\text{div}} Z(u) = 0$. Thus by (3.1)

$$X^{\vee} \overset{\vee}{\nabla} u = \overset{\vee}{\nabla} \sum_{l=1}^{\infty} \left[\left(1 - \frac{1}{l} \right) X_{+u_{l-1}} + \left(1 + \frac{1}{l+d-2} \right) X_{-u_{l+1}} \right] - Z(u). \tag{3.9}$$

This gives

$$\begin{aligned} & \|X \overset{\vee}{\nabla} u\|^2 \\ &= \sum_{l=1}^{\infty} \lambda_l \left(\left(1 - \frac{1}{l}\right) X_{+u_{l-1}} + \left(1 + \frac{1}{l+d-2}\right) X_{-u_{l+1}}, \left(1 - \frac{1}{l}\right) X_{+u_{l-1}} \right. \\ &\quad \left. + \left(1 + \frac{1}{l+d-2}\right) X_{-u_{l+1}} \right) + \|Z(u)\|^2 \\ &= \sum_{l=1}^{\infty} \lambda_l \left[\left(1 - \frac{1}{l}\right)^2 \|X_{+u_{l-1}}\|^2 + \left(1 + \frac{1}{l+d-2}\right)^2 \|X_{-u_{l+1}}\|^2 \right] \\ &\quad + \sum_{l=1}^{\infty} \lambda_l \left(1 - \frac{1}{l}\right) \left(1 + \frac{1}{l+d-2}\right) [(X_{+u_{l-1}}, X_{-u_{l+1}}) + (X_{-u_{l+1}}, X_{+u_{l-1}})] \\ &\quad + \|Z(u)\|^2. \end{aligned}$$

On the other hand, one has

$$\begin{aligned} & \|\overset{\vee}{\nabla} Xu\|^2 - (d-1)\|Xu\|^2 \\ &= -(d-1)\|X_{-u_1}\|^2 + \sum_{l=1}^{\infty} (\lambda_l - (d-1))(X_{+u_{l-1}} + X_{-u_{l+1}}, X_{+u_{l-1}} + X_{-u_{l+1}}) \\ &= -(d-1)\|X_{-u_1}\|^2 + \sum_{l=1}^{\infty} (\lambda_l - (d-1)) [\|X_{+u_{l-1}}\|^2 + \|X_{-u_{l+1}}\|^2] \\ &\quad + \sum_{l=1}^{\infty} (\lambda_l - (d-1)) [(X_{+u_{l-1}}, X_{-u_{l+1}}) + (X_{-u_{l+1}}, X_{+u_{l-1}})]. \end{aligned}$$

Somewhat miraculously, we observe that

$$\lambda_l \left(1 - \frac{1}{l}\right) \left(1 + \frac{1}{l+d-2}\right) = \lambda_l - (d-1).$$

This means that the two sums above involving $[(X_{+u_{l-1}}, X_{-u_{l+1}}) + (X_{-u_{l+1}}, X_{+u_{l-1}})]$ terms are equal. The Pestov identity from Proposition 3.1 now yields

$$\sum_{l=0}^{\infty} \alpha_l \|X_{-u_{l+1}}\|^2 - (R \overset{\vee}{\nabla} u, \overset{\vee}{\nabla} u) + \|Z(u)\|^2 + P(u, u) = \sum_{l=1}^{\infty} \beta_l \|X_{+u_{l-1}}\|^2$$

where α_l, β_l are as in (3.6)–(3.7). The result follows. □

Later on we shall need the following useful property.

Lemma 3.5 (Adjoint of T) *The formal adjoint of $T : C^\infty(\partial SM) \rightarrow \mathcal{Z}|_{\partial SM}$ satisfies*

$$\overset{\vee}{\operatorname{div}} T = -T^* \overset{\vee}{\nabla}$$

and the operator $\overset{\vee}{\operatorname{div}} T$ is self-adjoint in $L^2(\partial SM, d\Sigma^{2d-2})$.

Proof We use the Pestov identity with boundary term, to claim first that the operator $\overset{\vee}{\text{div}}T$ is self adjoint. Proposition 3.4 and the polarization identity imply that

$$P(u, w) = (X_+u, X_+w)_\beta - (X_-u, X_-w)_\alpha + (R\overset{\vee}{\nabla}u, \overset{\vee}{\nabla}w) - (Z(u), Z(w))$$

and since R is symmetric, it follows that $P(u, w) = P(w, u)$. But $P(u, w) = -(\overset{\vee}{\text{div}}T u, w)$ and thus $\overset{\vee}{\text{div}}T$ is self-adjoint. Hence

$$\overset{\vee}{\text{div}}T = (\overset{\vee}{\text{div}}T)^* = -T^*\overset{\vee}{\nabla}$$

as desired. □

4 Frequency localization

Recall from Sect. 2 that any $u \in C^\infty(SM)$ admits an L^2 -orthogonal decomposition

$$u = \sum_{l=0}^\infty u_l, \quad u_l \in \Omega_l,$$

where Ω_l corresponds to the set of vertical spherical harmonics of degree l . Since X_\pm maps Ω_l to $\Omega_{l\pm 1}$, it is immediate that the Pestov identity with boundary term (Proposition 3.4) reduces to the following identity when applied to functions in Ω_l (i.e. frequency localized Pestov identity).

Proposition 4.1 (Pestov identity on Ω_l with boundary term) *Let (M, g) be a compact manifold with smooth boundary, and let $l \geq 0$. One has*

$$\alpha_{l-1}\|X_-u\|^2 - (R\overset{\vee}{\nabla}u, \overset{\vee}{\nabla}u) + \|Z(u)\|^2 + P(u, u) = \beta_{l+1}\|X_+u\|^2, \quad u \in \Omega_l.$$

(We define $\alpha_{-1} = 0$.)

It was proved in [17] (and in [19, Appendix B] when $\dim(M) = 2$) that the frequency localized Pestov identity for all l is equivalent with the standard Pestov identity. The same is true in the boundary case:

Lemma 4.2 *The Pestov identity with boundary term on Ω_l is equivalent with the Pestov identity with boundary term in the following sense: for any $u \in C^\infty(SM)$, one has*

$$\begin{aligned} & \sum_{l=0}^\infty \left[\alpha_{l-1}\|X_-u_l\|^2 - (R\overset{\vee}{\nabla}u_l, \overset{\vee}{\nabla}u_l) + \|Z(u_l)\|^2 + P(u_l, u_l) - \beta_{l+1}\|X_+u_l\|^2 \right] \\ &= \|X_-u\|_\alpha^2 - (R\overset{\vee}{\nabla}u, \overset{\vee}{\nabla}u) + \|Z(u)\|^2 + P(u, u) - \|X_+u\|_\beta^2. \end{aligned}$$

The result will follow if we can show that the curvature, Z and P terms localise. Thus Lemma 4.2 is a corollary of the next result.

Lemma 4.3 *If (M, g) is a compact Riemannian manifold, then*

$$(R\overset{\vee}{\nabla}u, \overset{\vee}{\nabla}w) = 0, \quad (Z(u), Z(w)) = 0, \quad P(u, w) = 0$$

whenever $u \in \Omega_m, w \in \Omega_l$ and $m \neq l$. In particular

$$\overset{\vee}{\text{div}}T : \Omega_m \rightarrow \Omega_m.$$

Proof The localization of the curvature term was proved [17, Lemma 5.4]. We shall prove here that the Z -term localizes. That is enough to obtain also the conclusion for P since Proposition 3.4 and the polarization identity imply that

$$P(u, w) = (X_+u, X_+w)_\beta - (X_-u, X_-w)_\alpha + (R\overset{\vee}{\nabla}u, \overset{\vee}{\nabla}w) - (Z(u), Z(w)).$$

Hence the statements for the curvature and Z -term imply that $P(u, w) = 0$ when $m \neq l$. The last claim follows since $P(u, w) = -(\overset{\vee}{\text{div}}Tu, w)$.

The claim for $Z(u)$ for $d = 2$ follows from [17, Remark 6.5] using the explicit representation for $Z(u)$. To prove the claim when $d \geq 3$, recall that $Z(u)$ is the $\overset{\vee}{\text{div}}$ -free part of $\overset{h}{\nabla}u$ (the $\overset{\vee}{\text{div}}$ -free part is uniquely defined since there are no nontrivial harmonic 1-forms on S_xM when $d \geq 3$). Using the bracket relation $\overset{h}{\nabla} = \overset{\vee}{\nabla}X - X\overset{\vee}{\nabla}$ we can relate $X\overset{\vee}{\nabla}$ and $Z(u)$. Indeed this is done explicitly in equation (3.9), which shows that $Z(u)$ is the $\overset{\vee}{\text{div}}$ -free part of $-X\overset{\vee}{\nabla}u$. If we consider a coordinate system around a point x such that $\partial_{x_j}g_{kl}(x) = 0$ for all j, k, l and write $\overset{\vee}{\nabla}u = (\partial^k u)\partial_{x_k}$ as in [19, Appendix A], then at x

$$X\overset{\vee}{\nabla}u = v^j \partial_{x_j}(\partial^k u)\partial_{x_k} = v^j \partial^k(\partial_{x_j}u)\partial_{x_k} = v^j \overset{\vee}{\nabla}(\partial_{x_j}u).$$

Hence if we think of each v^j as 1-form it is enough to analyze the vertical Fourier decomposition of $A\overset{\vee}{\nabla}w$, where A is a scalar 1-form and $w = \partial_{x_j}u \in \Omega_m$. This is precisely the content of Lemma 4.4 below, and combining the statement of that lemma with (3.9) we see that $Z(u) = -B(u)$ where B is the operator in Lemma 4.4 for $X\overset{\vee}{\nabla}$. Since B localizes in frequency, the lemma is proved. \square

It remains to prove the following frequency localization statement.

Lemma 4.4 *Let $d = \dim M \geq 3$ and let $A \in \Omega_1$. For any $u_m \in \Omega_m$ one has*

$$A\overset{\vee}{\nabla}u_m = \overset{\vee}{\nabla}\alpha(u_m) + B(u_m)$$

where $B(u_m)$ is the $\overset{\vee}{\text{div}}$ -free part of $A\overset{\vee}{\nabla}u_m$. The map $B : C^\infty(SM) \rightarrow \mathcal{Z}$ satisfies

$$(B(u_m), B(w_l)) = 0, \quad m \neq l,$$

for any $u_m \in \Omega_m$ and $w_l \in \Omega_l$.

The proof uses the following lemma, which follows either by relating the Hodge and connection Laplacians via a Weitzenböck identity [22, Theorem 50] or by a direct computation in normal coordinates.

Lemma 4.5 *If u and v are 1-forms on a Riemannian manifold (M, g) and if $\Delta = d\delta + \delta d$ is the Hodge Laplacian, then*

$$\Delta(u \wedge v) = (\Delta u) \wedge v - 2 \sum_{j=1}^{\dim(M)} \nabla_{E_j}u \wedge \nabla_{E_j}v + u \wedge (\Delta v) + 2R(u^\sharp, v^\sharp, \cdot, \cdot)$$

where $\{E_1, \dots, E_n\}$ is any local orthonormal frame, ∇ is the Levi-Civita connection and R is the Riemann curvature tensor.

Proof of Lemma 4.4 This is a purely vertical statement and it is enough to argue for fixed $x \in M$. Moreover, since $S_x M$ is isometric to the standard sphere S^{d-1} , it is enough to prove the following statement: if $A \in \Omega_1$ and $u \in \Omega_m$, where Ω_k is the space of spherical harmonics of degree k on S^{d-1} , then

$$A du = d(\alpha(u)) + \delta(\beta(u)) \tag{4.1}$$

where β maps Ω_m into the set of exact 2-forms on S^{d-1} and satisfies

$$\Delta(\beta(u)) = (\lambda_m + d - 3)\beta(u) + h \tag{4.2}$$

where h is a harmonic 2-form (hence $h = 0$ for $d \geq 4$). Here d, δ and $\Delta = d\delta + \delta d$ are the exterior derivative, codifferential and Hodge Laplacian on S^{d-1} , respectively. If (4.1) and (4.2) have been proved, then we have

$$\begin{aligned} (\delta\beta(u_m), \delta\beta(w_l)) &= (\Delta\beta(u_m), \beta(w_l)) = \frac{\lambda_m + d - 3}{\lambda_l + d - 3}(\beta(u_m), \Delta\beta(w_l)) \\ &= \frac{\lambda_m + d - 3}{\lambda_l + d - 3}(\delta\beta(u_m), \delta\beta(w_l)). \end{aligned}$$

Thus $B(u_m) = \delta\beta(u_m)$ satisfies $(B(u_m), B(w_l)) = 0$ for $m \neq l$ as required.

The formula (4.1) follows directly from the Hodge decomposition on S^{d-1} , and $\beta(u)$ is an exact 2-form (recall that there are no harmonic 1-forms for $d \geq 3$). By taking the exterior derivative of (4.1), we also see that

$$\Delta(\beta(u)) = dA \wedge du.$$

Let $u \in \Omega_m$. We claim that

$$\Delta(dA \wedge du) = (\lambda_m + d - 3)dA \wedge du. \tag{4.3}$$

If (4.3) holds, then $\Delta(\Delta(\beta(u)) - (\lambda_m + d - 3)\beta(u)) = 0$, proving (4.2).

It remains to prove (4.3). By Lemma 4.5, for any local orthonormal frame $\{E_j\}$ of $T(S^{d-1})$ we have

$$\begin{aligned} \Delta(dA \wedge du) &= (\Delta dA) \wedge du - 2 \sum_{j=1}^{d-1} \nabla_{E_j} dA \wedge \nabla_{E_j} du + dA \wedge (\Delta du) \\ &\quad + 2R(dA^\sharp, du^\sharp, \cdot, \cdot) \\ &= (\lambda_m + d - 1)dA \wedge du - 2 \sum_{j=1}^{d-1} \nabla_{E_j} dA \wedge \nabla_{E_j} du + 2R(dA^\sharp, du^\sharp, \cdot, \cdot) \end{aligned}$$

using that $A \in \Omega_1, u \in \Omega_m$ and that Δ commutes with d . Now if $v \in S^{d-1}$ and $w \in T_v S^{d-1}$ with $|w| = 1$, and if $\gamma(t)$ is the geodesic on S^{d-1} with $\dot{\gamma}(0) = w$, one has

$$\nabla dA|_v(w, w) = \frac{d^2}{dt^2} A(\gamma(t)) \Big|_{t=0} = \frac{d^2}{dt^2} (a_j \gamma^j(t)) \Big|_{t=0} = -A(v)$$

using that geodesics are great circles. Thus $\nabla_{E_j} dA|_v(w) = -A(v)\langle E_j, w \rangle$, which gives that $\nabla_{E_j} dA|_v = -A(v)E_j^\flat$ and

$$\sum_{j=1}^{d-1} \nabla_{E_j} dA \wedge \nabla_{E_j} du = -A(v) \sum_{j=1}^{d-1} E_j^\flat \wedge \nabla_{E_j} du = -A(v)d(du) = 0.$$

Also, on the sphere we have $R(u^\sharp, v^\sharp, \cdot, \cdot) = -u \wedge v$. These facts imply (4.3). □

5 Stability for the transport equation

In this section we will prove the main stability estimate for solutions of the transport equation $Xu = f$ in SM when f has finite degree. In the next section we will give the more standard form where the solenoidal part of f is estimated in terms of $I_m f$.

Theorem 5.1 *Let (M, g) be a compact Riemannian manifold with smooth boundary and sectional curvature ≤ 0 , let $u \in C^\infty(SM)$, and write $f := Xu$. Suppose that f has finite degree m . If $m = 0$, then*

$$\|f\|_{L^2(SM)} \leq \|u\|_{H_T^{1/2}(\partial SM)}$$

whereas if $m \geq 1$, then

$$\|f - X(u_0 + \dots + u_{m-1})\|_{L^2(SM)} \leq \|u\|_{H_T^{1/2}(\partial SM)}.$$

5.1 Shifted Pestov identity with boundary terms

To prove Theorem 5.1 we first assume that $m \geq 1$, and discuss the case $m = 0$ later. We will try to estimate f in terms of $u|_{\partial SM}$ in suitable norms. The starting point is the identity from Proposition 4.1 with $l \geq 1$:

$$\alpha_{l-1} \|X_- u_l\|^2 - (R \overset{\vee}{\nabla} u_l, \overset{\vee}{\nabla} u_l) + \|Z(u_l)\|^2 + P(u_l, u_l) = \beta_{l+1} \|X_+ u_l\|^2.$$

Since we are assuming non-positive sectional curvature, we have

$$-(R \overset{\vee}{\nabla} u_l, \overset{\vee}{\nabla} u_l) + \|Z(u_l)\|^2 \geq 0$$

and thus

$$\alpha_{l-1} \|X_- u_l\|^2 + P(u_l, u_l) \leq \beta_{l+1} \|X_+ u_l\|^2.$$

We divide this estimate by α_{l-1} (always different from zero since $l \geq 1$), which corresponds to shifting the estimate down by one half vertical derivatives since $\alpha_{l-1} \sim l$. It follows that

$$\|X_- u_l\|^2 + \frac{1}{\alpha_{l-1}} P(u_l, u_l) \leq \frac{\beta_{l+1}}{\alpha_{l-1}} \|X_+ u_l\|^2.$$

The constant $\frac{\beta_{l+1}}{\alpha_{l-1}}$ is exactly $D_d(l)^2$ where $D_d(l)$ is as in [19, Lemma 5.1]. Note that $D_d(l) \leq 1$ for $d \geq 4$ and in the remaining cases it is sufficiently close to one for all practical purposes (when reading the proof it may be helpful to think that $D_d(l) \equiv 1$).

Thus we have the following inequality:

$$\|X_- u_l\|^2 + \frac{1}{\alpha_{l-1}} P(u_l, u_l) \leq D_d(l)^2 \|X_+ u_l\|^2. \tag{5.1}$$

For $l \geq m$ we have $X_- u_{l+2} + X_+ u_l = 0$ and using (5.1) we may write

$$\|X_- u_l\|^2 + \frac{1}{\alpha_{l-1}} P(u_l, u_l) \leq D_d(l)^2 \|X_- u_{l+2}\|^2.$$

Starting at $l = m$ and iterating this inequality N times leads to

$$\|X_{-u_m}\|^2 \leq \left[\prod_{j=0}^{N-1} D_d(m + 2j)^2 \right] \|X_{-u_{m+2N}}\|^2 - \sum_{j=0}^{N-1} \frac{\prod_{k=0}^{j-1} D_d(m + 2k)^2}{\alpha_{m-1+2j}} P(u_{m+2j}, u_{m+2j})$$

Write $\gamma_{d,m,j} = \prod_{k=0}^{j-1} D_d(m + 2k)^2$ and $\gamma_{d,m,0} = 1$. In the notation of [19, Theorem 1.1] one has $\gamma_{d,m,j} = \prod_{k=0}^{j-1} C_d(m - 1 + 2k)^2$, and thus $\gamma_{d,m,j} \leq c_d$ where

$$c_d = \begin{cases} 2, & d = 2, \\ 1.28, & d = 3, \\ 1, & d \geq 4. \end{cases} \tag{5.2}$$

Since $\|X_{-u_l}\|^2 \rightarrow 0$ as $l \rightarrow \infty$, we may take the limit as $N \rightarrow \infty$ to obtain

$$\|X_{-u_m}\|^2 \leq - \sum_{j=0}^{\infty} \frac{\gamma_{d,m,j}}{\alpha_{m-1+2j}} P(u_{m+2j}, u_{m+2j}). \tag{5.3}$$

The argument above gives a completely analogous inequality for $\|X_{-u_{m+1}}\|^2$, and adding these two inequalities leads to

$$\|X_{-u_m}\|^2 + \|X_{-u_{m+1}}\|^2 \leq - \sum_{k=0}^{\infty} b_{m,k} P(u_{m+k}, u_{m+k}) \tag{5.4}$$

where

$$b_{m,k} = \begin{cases} \frac{\gamma_{d,m,j}}{\alpha_{m-1+2j}}, & k = 2j, \\ \frac{\gamma_{d,m+1,j}}{\alpha_{m+2j}}, & k = 2j + 1. \end{cases}$$

Define $r := u_0 + u_1 + \dots + u_{m-1}$. Then the transport equation $Xu = f$ also gives

$$Xr + X_{-u_m} + X_{-u_{m+1}} = f \tag{5.5}$$

and thus $\|f - Xr\|^2 = \|X_{-u_m}\|^2 + \|X_{-u_{m+1}}\|^2$. This yields

$$\|f - Xr\|^2 \leq - \sum_{k=0}^{\infty} b_{m,k} P(u_{m+k}, u_{m+k}). \tag{5.6}$$

If we assume $m = 0$, then the equation $Xu = f$ implies $X_{-u_1} = f$, and (5.3) gives

$$\|f\|^2 \leq - \sum_{j=0}^{\infty} b_{1,2j} P(u_{1+2j}, u_{1+2j}) \leq - \sum_{k=0}^{\infty} b_{1,k} P(u_{1+k}, u_{1+k}). \tag{5.7}$$

Thus to prove Theorem 5.1 for $m \geq 0$, it remains to bound the right hand side of (5.6) for all $m \geq 1$.

5.2 The right hand side of (5.6): the space $H_T^{1/2}(\partial SM)$

Let $m \geq 1$. Motivated by (5.6) and the fact that P is defined in terms of the (horizontal) tangential operator T , we define a natural $H^{1/2}$ -space as follows. Define the $H_T^1(\partial SM)$ -norm

by setting

$$\|u\|_{H_T^1}^2 := \|u\|_{L^2}^2 + \|\overset{h}{\nabla}u\|_{L^2}^2.$$

The space $H_T^{1/2}(\partial SM)$ is defined by complex interpolation between L^2 and H_T^1 . The norm $H_T^{-1/2}$ is defined by duality, and then $H_T^{-1/2}$ is also the interpolation space between L^2 and H_T^{-1} (see [2, Corollary 4.5.2]).

Remark 5.2 Note that from (3.5) we have

$$\|Tu\|_{L^2} \leq \|\overset{h}{\nabla}u\|_{L^2} \tag{5.8}$$

$$\text{since } |Tu|^2 = \mu^2 |\overset{h}{\nabla}u|^2 + |Xu|^2 \leq (\mu^2 + \|v\|^2) |\overset{h}{\nabla}u|^2 = |v|^2 |\overset{h}{\nabla}u|^2 = |\overset{h}{\nabla}u|^2.$$

Now we use the key property of localization given by Lemma 4.3 to observe that

$$\sum_{k=0}^{\infty} b_{m,k} P(u_{m+k}, u_{m+k}) = P\left(\sum_{k=0}^{\infty} u_{m+k}, \sum_{l=0}^{\infty} b_{m,l} u_{m+l}\right).$$

We define an operator $B = B_m : C^\infty(\partial SM) \rightarrow C^\infty(\partial SM)$ by setting

$$Bu := \sum_{l=0}^{\infty} b_{m,l} u_{m+l}.$$

Since $m \geq 1$, the constant $b_{m,l}$ is well defined also when $l = 0$. Now (5.6) becomes

$$\|f - Xr\|^2 \leq -P(u, Bu) = -(Tu, \overset{\vee}{\nabla}Bu). \tag{5.9}$$

Here is the main claim:

Lemma 5.3 Given $u \in C^\infty(\partial SM)$ we have

$$|(Tu, \overset{\vee}{\nabla}Bu)| \leq \|u\|_{H_T^{1/2}}^2.$$

Proof We may write

$$(Tu, \overset{\vee}{\nabla}Bu) = -(B\overset{\vee}{\text{div}}Tu, u).$$

By the definitions, it suffices to show that

$$\|B\overset{\vee}{\text{div}}Tu\|_{H_T^{-1/2}} \leq \|u\|_{H_T^{1/2}}.$$

By interpolation, this follows from the next two inequalities

$$\|B\overset{\vee}{\text{div}}Tu\|_{L^2} \leq \|u\|_{H_T^1}, \tag{5.10}$$

$$\|B\overset{\vee}{\text{div}}Tu\|_{H_T^{-1}} \leq \|u\|_{L^2}. \tag{5.11}$$

To prove these estimates we first establish the property

$$\|\overset{\vee}{\nabla}Bu\|_{L^2} \leq \|u\|_{L^2}. \tag{5.12}$$

Indeed using the definition of B ,

$$\|\check{\nabla}Bu\|_{L^2}^2 = (Bu, \Delta Bu) = \sum_{l=0}^{\infty} \lambda_{m+l} b_{m,l}^2 \|u_{m+l}\|_{L^2}^2.$$

To prove (5.12) we will show that $\lambda_{m+l} b_{m,l}^2 \leq 1$ for $m \geq 1$ and $l \geq 0$. If $m = 1$ and $l = 0$, then $\lambda_1 b_{1,0}^2 = \frac{\lambda_1}{\alpha_0^2} = \frac{1}{d-1} \leq 1$, so we may assume $m, l \geq 1$. One has $\gamma_{d,m,j} \leq c_d$, which gives $\lambda_{m+l} b_{m,l}^2 \leq c_d^2 \frac{\lambda_{m+l}}{\alpha_{m-1+l}^2}$. Observe that simplifying (3.6) gives $\alpha_l = \frac{(2l+d-2)(l+d-1)}{l+d-2}$ for all $l \geq 1$. We thus have, writing $k = m + l \geq 2$,

$$\begin{aligned} \frac{\lambda_k}{\alpha_{k-1}^2} &= \frac{k(k+d-2)(k+d-3)^2}{(2k+d-4)^2(k+d-2)^2} \\ &= \frac{1}{4} \frac{k^3 + (2d-6)k^2 + (d-3)^2k}{(k^2 + (d-4)k + (\frac{d-4}{2})^2)(k+d-2)} \\ &= \frac{1}{4} \frac{k^3 + (2d-6)k^2 + (d^2-6d+9)k}{k^3 + (2d-6)k^2 + (d^2-6d+8 + (\frac{d-4}{2})^2)k + (d-2)(\frac{d-4}{2})^2}. \end{aligned}$$

Thus if $d = 2$ or $d \geq 6$, one has $(\frac{d-4}{2})^2 \geq 1$ and hence $\frac{\lambda_k}{\alpha_{k-1}^2} \leq \frac{1}{4}$. If $d = 3, 4, 5$ we estimate

$$\frac{\lambda_k}{\alpha_{k-1}^2} \leq \frac{1}{4} \frac{k^3 + (2d-6)k^2 + (d^2-6d+9)k}{k^3 + (2d-6)k^2 + (d^2-6d+8)k} \leq \frac{1}{4} \left[1 + \frac{1}{(k+d-3)^2-1} \right] \leq \frac{1}{3}$$

using $k \geq 2$. Combining these estimates with (5.2), we have

$$\lambda_{m+l} b_{m,l}^2 \leq c_d^2 \frac{\lambda_{m+l}}{\alpha_{m-1+l}^2} \leq 1.$$

The estimate (5.12) follows. Since $-\check{\nabla}B$ is the adjoint of $B\check{\text{div}}$, using (5.12) and (5.8) yields

$$\|B\check{\text{div}}Tu\|_{L^2} \leq \|Tu\|_{L^2} \leq \|u\|_{H_T^1}$$

thus proving (5.10).

Finally to prove (5.11), we note that $B\check{\text{div}}T = \check{\text{div}}TB$ by Lemma 4.3. Using Lemma 3.5 we may write

$$\begin{aligned} \|B\check{\text{div}}Tu\|_{H_T^{-1}} &= \sup_{\|h\|_{H_T^1}=1} (\check{\text{div}}TBu, h) \\ &= \sup_{\|h\|_{H_T^1}=1} -(T^*\check{\nabla}Bu, h) \\ &= \sup_{\|h\|_{H_T^1}=1} -(\check{\nabla}Bu, Th) \\ &\leq \sup_{\|h\|_{H_T^1}=1} \|u\|_{L^2} \|Th\|_{L^2} \\ &\leq \|u\|_{L^2}, \end{aligned}$$

where in the penultimate line we used (5.12) and (5.8). □

Theorem 5.1 for $m \geq 1$ now follows from (5.9) and Lemma 5.3. When $m = 0$, it follows from (5.7) and Lemma 5.3.

6 Stability for the solenoidal part

We now rewrite Theorem 5.1 in terms of the solenoidal part of the tensor inducing f and extend the result to H^1 regularity. Recall that the map

$$\ell_m : C^\infty(S^m(T^*M)) \rightarrow \bigoplus_{k=0}^{\lfloor m/2 \rfloor} \Omega_{m-2k},$$

is an isomorphism and it gives a natural identification between functions in Ω_m and *trace-free* symmetric m -tensors (for details on this see [5,8,19]). The identification actually holds pointwise for every $x \in M$. Moreover, the L^2 -norms on trace free symmetric m -tensors and functions in Ω_m are the same up to a constant depending only on d and m (cf. [5, Lemma 2.4]).

Given a tensor $\tilde{f} \in H^1(S^m(T^*M))$, we let $f = \ell_m \tilde{f}$ (using ℓ_m on H^1 spaces). Note if m is even (resp. odd), then f has zero odd (resp. even) Fourier modes. If $Xu = f$, we let

$$q := \sum_{k=0}^{\lfloor (m-1)/2 \rfloor} u_{m-2k-1}.$$

Upon defining $\tilde{q} := \ell_{m-1}^{-1}q$, the well-known relation $X\ell_{m-1} = \ell_m d^s$ implies that $\ell_m^{-1}(f - Xq) = \tilde{f} - d^s \tilde{q}$. To simplify the notation we shall drop the tildes, identify f with \tilde{f} , q with \tilde{q} and use that the L^2 -norms are equivalent.

We first collect regularity properties of solutions of transport equations involving H^1 tensor fields.

Lemma 6.1 *Let (M, g) be a compact simple manifold. Given $f \in H^1(S^m(T^*M))$, there is $u^f \in H^1(SM)$ satisfying*

$$Xu^f = -f \text{ in } SM, \quad u^f|_{\partial_- SM} = 0, \quad u^f|_{\partial_+ SM} = If. \tag{6.1}$$

Moreover, one has $u^f|_{\partial SM} \in H^1(\partial SM)$ and $If \in H_0^1(\partial_+ SM)$.

Proof If $f \in C^\infty(S^m(T^*M))$, define u^f on SM by

$$u^f(x, v) = \int_0^{\tau(x,v)} f(\varphi_t(x, v)) dt$$

where φ_t is the geodesic flow on SM . One has $u^f \in C^\infty(SM \setminus S(\partial M)) \cap C(SM)$ since the same is true for τ , and (6.1) holds for u^f . By [24, Corollary 1], the map $f \mapsto u^f$ extends as a bounded map $H^1(S^m(T^*M)) \rightarrow H^1(SM)$. (This boils down to the fact that $\nabla_v \tau$ and $\nabla_v^h \tau$, where the operator ∇_v^h is extended smoothly to SM , are uniformly bounded on $SM \setminus S(\partial M)$, see [23, Lemma 4.1.3] and [4, Lemma 5.1].) Moreover, by [23, Theorem 4.2.1] the map $f \mapsto If$ extends as a bounded map $H^1(S^m(T^*M)) \rightarrow H^1(\partial_+ SM)$. Then the properties (6.1) remain valid for $f \in H^1$ (the boundary value of u^f is in $H^{1/2}(\partial SM)$ by the trace theorem). Since If vanishes on the boundary of $\partial_+ SM$ when $f \in C^\infty$, one has $If \in H_0^1(\partial_+ SM)$ first for $f \in C^\infty$ and then for $f \in H^1$ by density. Since $u^f|_{\partial SM} = E_0(If)$

where E_0 denotes extension by zero from $\partial_+ SM$ to ∂SM , we have $u^f|_{\partial SM} \in H^1(\partial SM)$ when $f \in H^1$. □

Next we give a version of Theorem 5.1 for H^1 tensor fields. In its statement q is determined by u^f as described above.

Theorem 6.2 *Let (M, g) be a simply connected compact manifold with strictly convex boundary and sectional curvature ≤ 0 , and let $f \in H^1(S^m(T^*M))$. If $m = 0$, then*

$$\|f\|_{L^2(M)} \leq C \|u^f\|_{H_T^{1/2}(\partial SM)} \tag{6.2}$$

whereas if $m \geq 1$, then

$$\|f - d^s q\|_{L^2(M)} \leq C \|u^f\|_{H_T^{1/2}(\partial SM)}. \tag{6.3}$$

Here C only depends on d and m .

Proof Let $m \geq 1$ (the case $m = 0$ is analogous). Going back to (5.3) and using Lemma 5.3, one has the inequality

$$\|X_- u_m\|^2 + \|X_- u_{m+1}\|^2 \leq \|u\|_{H_T^{1/2}(\partial SM)}^2, \quad u \in C^\infty(SM).$$

Since functions in $H^1(SM)$ have traces in $H^{1/2}(\partial SM)$, and hence also in $H_T^{1/2}(\partial SM)$, the above inequality holds for $u \in H^1(SM)$ by density. Then it is enough to take $u = u^f$, where $u^f \in H^1(SM)$ by Lemma 6.1, and to note that by (5.5) and by equivalence of the L^2 norms

$$\|X_- u_m\|^2 + \|X_- u_{m+1}\|^2 = \|f - Xr\|_{L^2(SM)}^2 \geq c(d, m) \|f - d^s q\|_{L^2(M)}^2.$$

□

The estimate (6.2) for $m = 0$ is already in the form that we want, so we will focus on the case $m \geq 1$. Using the potential and solenoidal decomposition, we may write $f = f_s + d^s p$ where $\delta^s f_s = 0$ and p is an $(m - 1)$ -tensor such that $p|_{\partial M} = 0$. Let $w = p - q$. Then integrating by parts

$$\begin{aligned} \|f - d^s q\|^2 &= \|f_s + d^s w\|^2 \\ &= \|f_s\|^2 + 2(f_s, d^s w) + \|d^s w\|^2 \\ &= \|f_s\|^2 + 2(\iota_\nu f_s, w)_{\partial M} + \|d^s w\|^2 \\ &\geq \|f_s\|^2 - 2|(\iota_\nu f_s, q)_{\partial M}|. \end{aligned} \tag{6.4}$$

Next we observe that for any $\varepsilon > 0$

$$2|(\iota_\nu f_s, q)_{\partial M}| \leq \frac{1}{\varepsilon} \|q\|_{H^{1/2}(\partial M)}^2 + \varepsilon \|\iota_\nu f_s\|_{H^{-1/2}(\partial M)}^2. \tag{6.5}$$

We now claim:

Lemma 6.3 *We have*

$$\|\iota_\nu f_s\|_{H^{-1/2}(\partial M)} \lesssim \|f_s\|_{L^2(M)}.$$

Proof This is a duality argument, but it is important that $\delta^s f_s = 0$. Consider a bounded extension map for symmetric $(m - 1)$ -tensors, $e : H^{1/2}(\partial M) \rightarrow H^1(M)$ (such a map

can be constructed from a corresponding extension map for functions by working in local coordinates and using a partition of unity). Now write

$$\begin{aligned} \|\iota_v f_s\|_{H^{-1/2}(\partial M)} &= \sup_{\|h\|_{H^{1/2}(\partial M)}=1} \int_{\partial M} \langle \iota_v f_s, h \rangle dS \\ &= \sup_{\|h\|_{H^{1/2}(\partial M)}=1} (-\delta^s f_s, e(h)) + (f_s, d^s e(h)) \\ &= \sup_{\|h\|_{H^{1/2}(\partial M)}=1} (f_s, d^s e(h)) \\ &\lesssim \|f_s\|_{L^2(M)}. \end{aligned}$$

□

Combining (6.3)–(6.5) with Lemma 6.3 and choosing ε small enough, it follows that

$$\|f_s\|_{L^2(M)}^2 \lesssim \|u^f\|_{H_T^{1/2}(\partial SM)}^2 + \|q\|_{H^{1/2}(\partial M)}^2. \tag{6.6}$$

The next two lemmas will be useful when estimating the last term on the right.

Lemma 6.4 *Given $m \geq 0$, there is a constant $C > 0$ such that for any tensor q of order m*

$$\|q\|_{H^{1/2}(\partial M)} \leq C \|\ell_m q\|_{H_T^{1/2}(\partial SM)}.$$

Proof Recall that we identify symmetric m -tensors with functions in $\bigoplus_{k=0}^{\lfloor m/2 \rfloor} \Omega_{m-2k}$ via ℓ_m as explained at the beginning of this section. By interpolation, it is enough to show that $\|\ell_m^{-1} h\|_{L^2} \lesssim \|h\|_{L^2}$ and $\|\ell_m^{-1} h\|_{H^1} \lesssim \|h\|_{H_T^1}$ when $h \in \bigoplus_{k=0}^{\lfloor m/2 \rfloor} \Omega_{m-2k}$. The first inequality follows from the equivalence of the L^2 -norms. For the second inequality, observe that locally a symmetric m -tensor field can be written as $q = q_{i_1 \dots i_m} dx^{i_1} \otimes \dots \otimes dx^{i_m}$. The H^1 -norm of q in ∂M consists of the L^2 -norm of q plus the L^2 norm of the components $q_{i_1 \dots i_m}(x)$ tangentially to M . Locally $\ell_m q$ has the form $q_{i_1 \dots i_m} v^{i_1} \dots v^{i_m}$. When we apply ∇^h to $\ell_m q$ all the tangential derivatives in the direction of ∂M will appear. There will also be some vertical derivatives (involving the Christoffel symbols), but since $\ell_m q$ is a polynomial of degree m in v , these terms can all be controlled by the L^2 -norm of $\ell_m q$. Thus $\|q\|_{H^1} \lesssim \|\ell_m q\|_{H_T^1}$ follows, and this may be rewritten as $\|\ell_m^{-1} h\|_{H^1} \lesssim \|h\|_{H_T^1}$. □

Lemma 6.5 (The $H_T^1(\partial SM)$ norm localizes in frequency) *One has*

$$\|u\|_{H_T^1(\partial SM)}^2 = \sum_{m=0}^{\infty} \|u_m\|_{H_T^1(\partial SM)}^2$$

for all $u \in H_T^1(\partial SM)$. In particular, $\|\sum_{l=0}^m u_l\|_{H_T^1(\partial SM)} \leq \|u\|_{H_T^1(\partial SM)}$ when $m \geq 0$.

Proof The proof is somewhat indirect and is based on the following observations.

- (1) Let W be a vector field on M and let $\mathbb{W} = (W, 0)$ be its horizontal lift to SM . Then $\Delta \mathbb{W} = \mathbb{W} \Delta$ where Δ is the vertical Laplacian. This can be seen by taking a geodesic coordinate neighbourhood around a point x , so that $\partial_j g_{kl}(x) = 0$ for all j, k, l . In that case if we write $W = w^i(x) \partial_{x_i}$, then $(\mathbb{W}u)(x, v) = w^i(x) \frac{\partial u}{\partial x_i}$ and thus $\mathbb{W} : \Omega_m \rightarrow \Omega_m$. (Another way to prove this is to check that $[\delta_j, \Delta] = 0$, using the notation and commutator formulas in [19, Appendix A].)

- (2) There is a neighbourhood U_ε of ∂M in M diffeomorphic to $\partial M \times [0, \varepsilon)$ via $\partial M \times [0, \varepsilon) \ni (x, t) \mapsto \exp_x(-tv(x)) \in U_\varepsilon$. This allows us to naturally extend to U_ε the exterior unit normal ν to a vector field, still denoted by ν .
- (3) A smooth function $u \in C^\infty(\partial SM)$ can be extended to a smooth function $u^\nu \in C^\infty(SU_\varepsilon)$ simply by making it constant on the orbits of the flow of ν , the horizontal lift of ν . By item (1) we have

$$(u_m)^\nu = (u^\nu)_m \tag{6.7}$$

- (4) Let f_t be the flow of ν in SM , and let V_ε be the neighbourhood of ∂SM in SM diffeomorphic to $\partial SM \times [0, \varepsilon)$ via $(x, v, t) \mapsto f_{-t}(x, v)$. Since $f_{-t}(x, v) = (x(t), v(t))$ where $x(t) = \exp_x(-tv)$ is the normal geodesic and $v(t)$ is the parallel transport of v along $x(t)$, one has $V_\varepsilon = SU_\varepsilon$ (the map $v \mapsto v(t)$ is bijective from $S_x M$ onto $S_{x(t)} M$).

Let $u \in C^\infty(\partial SM)$. The fact that $\nu(u^\nu) = 0$ implies that $\overset{h}{\nabla} u = (\overset{h}{\nabla} u^\nu)|_{\partial SM}$ and thus for $(x, v) \in \partial SM$ we have

$$\lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \int_0^\varepsilon |\overset{h}{\nabla} u^\nu(x, v, t)|^2 dt = |\overset{h}{\nabla} u(x, v)|^2.$$

Integrating over ∂SM and using that $V_\varepsilon = SU_\varepsilon$ by (4), this gives

$$\lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \|\overset{h}{\nabla} u^\nu\|_{L^2(SU_\varepsilon)}^2 = \|\overset{h}{\nabla} u\|_{L^2(\partial SM)}^2. \tag{6.8}$$

We now recall that it is possible to write for any $w \in C^\infty(SU_\varepsilon)$ (all norms in $L^2(SU_\varepsilon)$), cf. [12, proof of Lemma 5.1]:

$$\|\overset{h}{\nabla} w\|^2 = \|Z(w)\|^2 + \|X_- w_1\|^2 + \sum_{l=1}^\infty A(d, l) \|X_+ w_{l-1}\|^2 + B(d, l) \|X_- w_{l+1}\|^2, \tag{6.9}$$

where $A(d, l) = 2 + \frac{d-2}{2}$ and $B(d, l) = 2 + \frac{1}{d+l-2}$. By Lemma 4.3 one may write $\|Z(w)\|^2 = \sum \|Z(w_m)\|^2$, and thus using (6.9) for $w = u^\nu$ and $w = (u^\nu)_m$ for each m we deduce

$$\|\overset{h}{\nabla} u^\nu\|_{L^2(SU_\varepsilon)}^2 = \sum_{m=0}^\infty \|\overset{h}{\nabla} (u^\nu)_m\|_{L^2(SU_\varepsilon)}^2.$$

Dividing this by ε and taking the limit as $\varepsilon \rightarrow 0$, the identities (6.7) and (6.8) yield

$$\|\overset{h}{\nabla} u\|_{L^2(\partial SM)}^2 = \sum_{m=0}^\infty \|\overset{h}{\nabla} u_m\|_{L^2(\partial SM)}^2.$$

This implies the desired claim for $u \in C^\infty(\partial SM)$, and the result follows since $C^\infty(\partial SM)$ is dense in $H_T^1(\partial SM)$. (The density claim can be proved by using a partition of unity, convolution approximation in coordinate neighborhoods, and the Friedrichs lemma [9, Lemma 17.1.5].) □

We now put the arguments above together to derive:

Theorem 6.6 *Let (M, g) be a simply connected compact manifold with strictly convex boundary and non-positive sectional curvature. Given $m \geq 0$ there is a constant $C > 0$ such that for any $f \in H^1(S^m(T^*M))$, one has*

$$\|f_s\|_{L^2(M)} \leq C \|u^f\|_{H_T^{1/2}(\partial SM)}.$$

Proof For $m = 0$ this is just (6.2), so we assume $m \geq 1$. Combining (6.6) and Lemma 6.4 we derive

$$\|f_s\| \lesssim \|u^f\|_{H_T^{1/2}} + \|\ell_{m-1}q\|_{H_T^{1/2}}^2.$$

Recall that $\ell_{m-1}q = \sum_{k=0}^{[(m-1)/2]} u_{m-2k-1}^f$. Interpolating the bound $\|\sum_{k=0}^{[(m-1)/2]} u_{m-2k-1}\|_{L^2(\partial SM)} \leq \|u\|_{L^2(\partial SM)}$ for $u \in L^2(\partial SM)$ with the bound in Lemma 6.5 gives

$$\left\| \sum_{k=0}^{[(m-1)/2]} u_{m-2k-1} \right\|_{H_T^{1/2}} \leq \|u\|_{H_T^{1/2}}, \quad u \in H_T^{1/2}(\partial SM),$$

and the result follows by taking $u = u^f$. □

We can refine this further and prove Theorem 1.3 in the introduction. Define the space $H_T^{1/2}(\partial_+ SM)$ as the interpolation space between $H_T^1(\partial_+ SM)$ and $L^2(\partial_+ SM)$.

Proof of Theorem 1.3 Theorem 6.6 gives

$$\|f_s\|_{L^2(M)} \leq C \|E_0(I f)\|_{H_T^{1/2}(\partial SM)} \tag{6.10}$$

where E_0 is extension by zero from $\partial_+ SM$ to ∂SM . We define $H_{T,0}^1(\partial_+ SM)$ as the closure of $C_c^\infty((\partial_+ SM)^{\text{int}})$ with respect to the H_T^1 -norm, and $H_{T,0}^{1/2}(\partial_+ SM)$ as the interpolation space between L^2 and $H_{T,0}^1(\partial_+ SM)$. Since E_0 is bounded $H_{T,0}^1(\partial_+ SM) \rightarrow H_T^1(\partial SM)$ and $L^2(\partial_+ SM) \rightarrow L^2(\partial SM)$, it is also bounded

$$E_0 : H_{T,0}^{1/2}(\partial_+ SM) \rightarrow H_T^{1/2}(\partial SM). \tag{6.11}$$

Now, if $f \in H^1(S^m(T^*M))$, then $I f$ is in $H_0^1(\partial_+ SM)$ by Lemma 6.1 and hence also in the larger space $H_{T,0}^{1/2}(\partial_+ SM)$. Combining (6.10) and (6.11) proves the result. □

Remark 6.7 Theorem 1.3 remains true for $f \in H^{1/2}(S^m(T^*M))$ by density, since I is bounded $H^{1/2}(S^m(T^*M)) \rightarrow H^{1/2}(\partial_+ SM)$ by [23, Theorem 4.2.1] and interpolation. It would be interesting if one could prove Theorem 1.3 for $f \in L^2(S^m(T^*M))$. However, in general we do not know if I is bounded $L^2(S^m(T^*M)) \rightarrow H_T^{1/2}(\partial_+ SM)$. Also, our approach with the Pestov identity as it stands is unable to produce stability estimates for higher order Sobolev norms.

Acknowledgements We are very grateful to the referee for several comments that improved the presentation and in particular for suggesting a simplified proof of Lemma 4.4. GPP was supported by EPSRC Grant EP/R001898/1 and the Leverhulme trust. MS was supported by the Academy of Finland (Finnish Centre of Excellence in Inverse Modelling and Imaging, Grant Numbers 312121 and 309963) and by the European Research Council under Horizon 2020 (ERC CoG 770924). This material is based upon work supported by the National Science Foundation under Grant No. 1440140, while the authors were in residence at MSRI in Berkeley, California, during the semester on Microlocal Analysis in 2019.

Open Access This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article’s Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article’s Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit <http://creativecommons.org/licenses/by/4.0/>.

References

1. Assylbekov, Y., Stefanov, P.: Sharp stability estimate for the geodesic ray transform. *Inverse Probl.* **36**, 025013 (2020)
2. Bergh, J., Löfström, J.: *Interpolation Spaces*. Springer, Berlin (1976)
3. Boman, J., Sharafutdinov, V.: Stability estimates in tensor tomography. *Inverse Probl. Imaging* **12**, 1245–1262 (2018)
4. Dairbekov, N., Paternain, G.P., Stefanov, P., Uhlmann, G.: The boundary rigidity problem in the presence of a magnetic field. *Adv. Math.* **216**, 535–609 (2007)
5. Dairbekov, N.S., Sharafutdinov, V.A.: On conformal Killing symmetric tensor fields on Riemannian manifolds. *Sib. Adv. Math.* **21**, 1–41 (2011)
6. Guillarmou, C.: Lens rigidity for manifolds with hyperbolic trapped sets. *J. Am. Math. Soc.* **30**, 561–599 (2017)
7. Guillarmou, C., Mazzucchelli, M., Tzou, L.: Boundary and lens rigidity for non-convex manifolds. *Am. J. Math.*
8. Guillemin, V., Kazhdan, D.: Some inverse spectral results for negatively curved n -manifolds. In: *Geometry of the Laplace Operator (Proc. Sympos. Pure Math., Univ. Hawaii, Honolulu, Hawaii, 1979)*, Proc. Sympos. Pure Math., vol. XXXVI, pp. 153–180. Amer. Math. Soc., Providence (1980)
9. Hörmander, L.: *The Analysis of Linear Partial Differential Operators*, vols. I–IV. Springer (1983–1985)
10. Ilmavirta, J., Paternain, G.P.: Broken ray tensor tomography with one reflecting obstacle. *Commun. Anal. Geom.* [arXiv:1805.04947](https://arxiv.org/abs/1805.04947)
11. Knieper, G.: Hyperbolic dynamics and Riemannian geometry. In: *Handbook of Dynamical Systems*, vol. 1A, pp. 453–545. North-Holland, Amsterdam (2002)
12. Lehtonen, J., Railo, J., Salo, M.: Tensor tomography on Cartan–Hadamard manifolds. *Inverse Probl.* **34**(4), 044004 (2018). (p 27)
13. Monard, F.: Functional relations, sharp mapping properties and regularization of the X-ray transform on disks of constant curvature. *SIAM J. Math. Anal.*
14. Monard, F., Nickl, R., Paternain, G.P.: Efficient nonparametric Bayesian inference for X-ray transforms. *Ann. Stat.* **47**, 1113–1147 (2019)
15. Natterer, F.: *The Mathematics of Computerized Tomography*, Classics in Applied Mathematics, vol. 32. SIAM, Philadelphia (2001) (**Reprint of the 1986 original**)
16. Paternain, G.P.: *Geodesic Flows*, Progress in Mathematics, vol. 180. Birkhäuser (1999)
17. Paternain, G.P., Salo, M.: Carleman estimates for geodesic X-ray transforms. [arXiv:1805.02163](https://arxiv.org/abs/1805.02163)
18. Paternain, G.P., Salo, M., Uhlmann, G.: Tensor tomography on simple surfaces. *Invent. Math.* **193**, 229–247 (2013)
19. Paternain, G.P., Salo, M., Uhlmann, G.: Invariant distributions, Beurling transforms and tensor tomography in higher dimensions. *Math. Ann.* **363**, 305–362 (2015)
20. Paternain, G.P., Salo, M., Uhlmann, G.: *Geometric Inverse Problems in Two Dimensions*, Textbook in Progress
21. Pestov, L., Sharafutdinov, V.A.: Integral geometry of tensor fields on a manifold of negative curvature. *Sib. Math. J.* **29**, 427–441 (1988)
22. Petersen, P.: *Riemannian Geometry*, 2nd edn. Springer, Berlin (2006)
23. Sharafutdinov, V.A.: *Integral Geometry of Tensor Fields*, Inverse and Ill-Posed Problems Series. VSP, Utrecht (1994)
24. Sharafutdinov, V.A.: Finiteness theorem for the ray transform on a Riemannian manifold. *Inverse Probl.* **11**, 1039–1050 (1995)
25. Sharafutdinov, V.A.: Variations of Dirichlet-to-Neumann map and deformation boundary rigidity of simple 2-manifolds. *J. Geom. Anal.* **17**, 147–187 (2007)
26. Stefanov, P., Uhlmann, G.: Stability estimates for the X-ray transform of tensor fields and boundary rigidity. *Duke Math. J.* **123**, 445–467 (2004)
27. Stefanov, P., Uhlmann, G., Vasy, A.: Inverting the local geodesic X-ray transform on tensors. *J. Anal. Math.* **136**, 151–208 (2018)
28. Uhlmann, G., Vasy, A.: The inverse problem for the local geodesic ray transform. *Invent. Math.* **205**, 83–120 (2016)